



NATIONAL OPEN UNIVERSITY OF NIGERIA

SCHOOL OF SCIENCE AND TECHNOLOGY

COURSE CODE: MTH 422

COURSE TITLE: PARTIAL DIFFERENTIAL EQUATIONS

**COURSE
GUIDE****MTH 422
PARTIAL DIFFERENTIAL EQUATIONS**

Course Team Prof. O. J. Adeniran (Course Developer/Writer) –
UNAB, Abeokuta
Dr. Abiola Bankole – UNILAG
Dr. S. O. Ajibola (Course Editors/Programme
Leader) – NOUN

**NATIONAL OPEN UNIVERSITY OF NIGERIA**

National Open University of Nigeria
Headquarters
14/16 Ahmadu Bello Way
Victoria Island, Lagos

Abuja Office
5 Dar es Salaam Street
Off Aminu Kano Crescent
Wuse II, Abuja

e-mail: centralinfo@nou.edu.ng

URL: www.nou.edu.ng

Published by
National Open University of Nigeria

Printed 2011

Reprinted 2014

ISBN: 978-058-720-9

All Rights Reserved

CONTENTS**PAGE**

Introduction.....	iv
What you will Learn in this Course.....	iv
Course Aim.....	v
Course Objectives.....	v
Working through this Course.....	vi
Course Materials.....	vii
Study Units.....	vii
Textbooks and References.....	vii
Assignment File.....	viii
Assessment.....	viii
Tutor-Marked Assignment.....	ix
Final Examination and Grading.....	ix
Presentation Schedule.....	ix
Course Marking Scheme.....	ix
Course Overview.....	x
How to Get the Most from this Course.....	x
Facilitators, Tutors and Tutorials.....	xii
Summary.....	xii

INTRODUCTION

MTH 422: Partial Differential Equations: Is a course designed for 400 level undergraduates running the B.Sc. degree in Mathematics.

This course guide tells you briefly what the course is all about, the course materials you will need and how you can derive maximum benefit from the customised self-instructional materials. It also provides hints on your Tutor-Marked Assignments, details of which will be given to you at your study centre. Tutorial sessions, where you can seek clarifications on the course materials will be arranged for you at your centre. It is in your own interest to attend the sessions. The time and venue will be made known to you at your centre.

The four-module course is designed to equip the students with the methods, approaches, and strategies required teaching some concepts of mathematics. The modules introduce you to Partial Differential Equations.

WHAT YOU WILL LEARN IN THIS COURSE

Partial Differential Equations are used to describe and identically formalise a wide range of real world events like sound, heat, electrostatics, electromagnetism, electrodynamics, fluid flow and mechanical displacement to show that they are governed by the same underlying dynamic; and presumably you must have at an earlier time become familiar with basics in the prerequisite to this course. Through this course therefore, you will be encouraged to develop an enquiring attitude towards Partial Differential Equations and relate the lessons learnt to the universe around you and which abounds with ceaseless applications of Partial Differential Equations.

It is the objectives of this course to build upon the lessons learnt in the prerequisite course, and formally to introduce to you the more advanced concept of Partial Differential Equations with the view to greater strengthening your understanding of the underlying principles at work upon which developmental research in this highly specialised area of mathematics are based.

This course comprises a total of 7 units distributed across 4 modules as follows:

Module 1 is composed of 2 units

Module 2 is composed of 2 units

Module 3 is composed of 2 units

Module 4 is composed of 1 unit

Module 1 unit 1 will bring you up to speed on the Essential Definitions pertinent to the study of Partial Differential Equations. In this unit we will show you how to recognise first Order Equation, Quasi – Linear Equations and use the Method of Lagrange in solving them. In unit 2, we will guide you through a test case scenario where you shall apply Partial Differential Equation to the formulation of the Conservation Law and ultimately derive the conceptual Development of Shock.

Module 2 will allow you to work with General First Order Equation in unit 1 focusing on the Cauchy Method of Characteristic for Partial Differential Equation. In unit 2 you will be shown that there are three Types of Solution; the Complete Solution (Integral), the General Solution (Integral) and the Singular Solution respectively.

Module 3 will allow us move up to higher order Partial Differential Equations; specifically Second Order Partial Differential Equations in unit 1 where you shall learn about their Classifications and the Tricomi's Equation, its Characteristics and learn about the Case of Two Independent Variables. We shall see that expediency at times dictates that we apply Transformation of Independent Variables in arriving at a solution for Partial Differential Equations in unit 2 with the view to recognising the Regular Case, the Hyperbolic Case and the Elliptic Case.

Unit 1 of Module 4 brings to the fore the Cauchy Problem which you shall learn; as well as the Characteristics Problem, the Fundamental Existence Theorem and you shall complete this course only after knowing and understanding the Kovalevsky theorem.

COURSE AIM

Our aim through MTH 422 is to further deepen your understanding of Partial Differential Equations and acquaint you with the graphical and mathematical significance of Partial Differential Equations through calculations and examples which lets you establish the practicable applications and indispensability of Partial Differential Equations in the world we live in.

COURSE OBJECTIVES

On your part we expect you in turn to conscientiously and diligently work through this course upon completion of which you should be able to:

- properly define the term Partial Differential Equation
- classify first order equations

- investigate the methods for constructing solutions for partial differential equations
- solve quasi – Linear Equations
- explore the many definitions applied in deriving solutions
- apply the method of Lagrange in deriving solutions for partial differential equations
- study Conservation Law
- explain the concept of shock
- study in detail the class referred to as General non-linear First Order Equation
- sketch and explain the Monge cone
- apply Cauchy Method of Characteristic equations
- categorise the different types of solution of Partial Differential Equations
- explain the methods used in deriving complete solution
- discuss the meaning of a General Solution
- explain why some Partial Differential Equations are singular solutions
- classify Second Order Partial Differential Equations
- explain the importance of the Eigen-values of the matrix of coefficients
- state Tricomi's Equation
- work with Laplace, heat and Wave Equations
- study the special case of two independent variables
- transform independent variables
- describe the theorems that apply to the regular case
- solve equations of the hyperbolic types by transformations
- give reasons why Elliptic equations have no real characteristics
- describe Cauchy Problem and Characteristics Problem
- discuss the meaning of the strip condition
- treat the fundamental existence theorem
- take a critical look at Cauchy problem
- solve problems using the Cauchy Kowalevski theorem

WORKING THROUGH THIS COURSE

This course requires you to spend quality time to read. Whereas the content of this course is quite comprehensive, it is presented in clear mathematical language that you can easily relate to. The presentation style of this course is adequate and the content easy to assimilate.

You should take full advantage of the tutorial sessions because this is a veritable forum for you to “rub minds” with your peers – which provides

you valuable feedback as you have the opportunity of comparing knowledge with your course mates.

COURSE MATERIALS

You will be provided with the course material prior to commencement of this course, which will comprise your Course Guide as well as your Study Units. You will receive a list of recommended textbooks which shall be an invaluable asset for your course material. These textbooks are however not compulsory. You will also receive Assignment File and Presentation Schedule to work with.

STUDY UNITS

You will find listed below the study units which are contained in this course and you will observe that there are 4 modules. Each module comprises 2 units each, except for Module 4 which has 1 unit.

Module 1

- Unit 1 Definitions and Equations
- Unit 2 Application of IVP Conservation Law, Development of Shock

Module 2

- Unit 1 General First Order Equation and Cauchy Method of Characteristic
- Unit 2 Types of Solution

Module 3

- Unit 1 Second Order P.D.E. Classifications
- Unit 2 Transformation of Independent Variables

Module 4

- Unit 1 Cauchy Problem, Characteristics Problem and Fundamental Existence Theorem

TEXTBOOKS/ REFERENCES

There are more recent editions of some of the recommended textbooks and you are advised to consult the newer editions for your further reading.

- Adomian, G. (1994). *Solving Frontier Problems of Physics: The Decomposition Method*. Kluwer Academic Publishers.
- Courant, R. & Hilbert, D. (1962). *Methods of Mathematical Physics II*. New York: Wiley-Interscience.
- Evans, L. C. (1998). "Partial Differential Equations." Providence. *American Mathematical Society*.
- Jost, J. (2002). *Partial Differential Equations*. New York: Springer-Verlag.
- Petrovskii, I. G. (1967). *Partial Differential Equations*. Philadelphia: W. B. Saunders Co.
- Pinchover, Y. & Rubinstein, J. (2005). *An Introduction to Partial Differential Equation*. New York: Cambridge University Press.
- Polyanin, A. D. & Zaitsev, V. F. (2004). *Handbook of Non-linear Partial Differential Equations*. Boca Raton: Chapman & Hall/CRC Press.
- Polyanin, A. D. (2002). *Handbook of Linear Partial Differential Equations for Engineers and Scientists*. Boca Raton: Chapman & Hall/CRC Press.
- Polyanin, A. D, Zaitsev, V. F. & Moussiaux, A. (2002). *Handbook of First Order Partial Differential Equations*. London: Taylor & Francis.
- Wazwaz, Abdul-Majid. (2009). *Partial Differential Equations and Solitary Waves Theory*. Higher Education Press.

ASSIGNMENT FILE

You will find details of works you are to submit to your tutor for marking in your assignment file. The marks you obtain for your assignments will count towards the final mark you obtain for this course. Further information on assignments will be found in the assignment file itself and in the assessment section of this course guide. Each unit of this course has some assignments. These assignments are meant to help you understand the course and assess your progress.

ASSESSMENT

Assessment of your performance is partly through Tutor-Marked Assignments which you can refer to as TMAs, and partly through the End of Course Examinations.

TUTOR-MARKED ASSIGNMENT

This is basically Continuous Assessment which accounts for 30% of your total score. During this course you will be given 4 Tutor-Marked Assignments and you must answer three of them to qualify to sit for the end of year examinations. Tutor-Marked Assignments are provided by your Course Facilitator and you must return the answered Tutor-Marked Assignments back to your Course Facilitator within the stipulated period.

FINAL EXAMINATION AND GRADING

The end of course examination for this course will be about three hours, and will account for 70% of the total course score. The questions will be fashioned after the self-testing, practice exercise and tutor-marked assignments that you have previously encountered during your course. All areas of the course will be examined.

Utilise the time between the last unit and the commencement of your examination to revise the whole course. You might find it useful to review your self-test, TMAs, and comments on them before the examination. The end of course examination covers information from all parts of the course material.

END OF COURSE EXAMINATION

You must sit for the End of Course Examination which accounts for 70% of your score upon completion of this course. The time for the examination is not fixed, but you will be given adequate notice of the examination date, time and the venue, which may, or may not coincide with National Open University of Nigeria semester examination.

PRESENTATION SCHEDULE

Dates for prompt completion and submission of your TMAs and attendance of tutorials will be reflected in your course materials. You should remember to submit all assignments at the stipulated date and time. You should work as scheduled, and do not lag behind in your work.

COURSE MARKING SCHEME

Assessment	Marks
Assignments 1-4	the best three (3) of the four Assignments will be rated based on 10% each, making a total of 30% of the course marks.
End of course examination	70% of overall course marks.
Total	100%

HOW TO GET THE MOST FROM THIS COURSE

- 1 In distance learning, the study units replace the university lectures. This is one of the great advantages of distance learning; you can read and work through specially designed study materials at your own pace, and at a time and place that suits you. Realise the fact that you are reading the lecture instead of listening to the lecturer. In the same way, a lecturer might assign you some reading materials. The study units tell you when to read, your text materials and recommended books for your further reading. You are provided exercises to attempt at appropriate point in time, just as a lecturer might give in a classroom situation.
- 2 Each of the study units follows a common format. The first item is an introduction to the subject matter of the unit, and how a particular unit is integrated with other units, and the course as a whole. Next to this is a set of learning objectives. These objectives state the mental tasks you should be able to accomplish by the time you have completed the unit. These learning objectives are therefore, meant to guide your study. The moment a unit is finished, you must go back and check whether you have achieved the objectives. If this is made a habit, you will significantly improve your chances of passing the course.
- 3 The main body of the unit guides you through the required reading from other sources; this is either from your references or a reading section.
- 4 The following is a practical strategy for working through the course: If you run into any trouble, telephone your tutor or visit the study centre nearest to you. Remember, your tutor's job is to help you. When you need assistance, do not hesitate to ask your tutor to provide it.

- 5 Read this Course Guide thoroughly; this is your first assignment!
- 6 Organise a Study Schedule; Design a 'Course Overview' to guide you through the course. Note the time you are expected to spend on each unit and how the assignments relate to the units. Important information, e.g. details of your tutorials, and the date of the first day of the semester is available at the centre. You need to gather all the information into one place, such as your diary or a wall calendar. Decide on whatever method you choose, and write in your own dates and schedule of work for each unit.
- 7 Once you have created your own study schedule, do everything to stay faithful to it. The major reason why students fail is that they lag behind in their course work. If you get into difficulties with your schedule, please, let your tutor know before it is too late for help.
- 8 Turn to unit 1, and read the instruction and the objectives for the unit.
- 9 Assemble the study materials. You will need your references and the unit you are studying at any point in time.
- 10 As you work through the unit, you will know what sources to consult for further information.
- 11 Visit your study centre whenever you need up-to-date information.
- 12 Before the relevant due dates (about 4 weeks before due dates), visit your study centre for your next required assignment. Keep in mind that you will learn a lot by doing the assignments carefully. They have been designed to help you meet the objectives of the course and, therefore, will help you pass the examination. Submit all assignments as at when due.
- 13 Review the objectives for each study unit to confirm that you have achieved them. If you are not sure about any of the objectives, you can move to the next unit. Study unit by unit through the course, and try to space your study so that you can keep to the schedule.
- 14 When you have submitted an assignment to your tutor for marking, do not wait for its return before starting the next unit. Keep to your schedule. When the assignment is returned, pay particular attention to tutor's comments, both on the tutor-marked

assignment form and also the written comments on the ordinary assignments.

- 15 After completing the last unit, review the course and prepare yourself for the final examination. Check that you have achieved the unit objectives (listed at the beginning of each unit), and the course objectives (listed in the Course Guide).

FACILITATORS, TUTORS AND TUTORIALS

There are some hours of tutorial provided in support of this course. You will be notified of the dates, times and venue of these tutorials, as well as the name, and phone number of your facilitator as soon as you are fixed in a tutorial group.

Your tutor or facilitator will mark and comment on your assignments. Your tutor keeps a close watch on your progress, so as to render necessary assistance when required. You mail your tutor-marked assignment to your tutor before the scheduled date. They will be marked by your tutor and returned to you as soon as possible.

Do not hesitate to contact your facilitator by telephone, e-mail, and discuss your problems for necessary assistance.

The following might be circumstances in which you would find help necessary. Contact your facilitator if you:

- do not understand any part of the study units of the assigned readings
- have difficulty with the self-test or exercises
- have a question or problem with an assignment or with the grading of an assignment.

You should try your best to attend the tutorials. This is the only chance for a face-to-face contact with your course facilitator, and to ask questions which are answered instantly. You can raise any problems encountered in the course of your study. To derive maximum benefit from course tutorials, prepare a list of questions before the tutorial session. You will learn a lot by your active participation in the discussion.

SUMMARY

Each of the 4 modules of this course has been designed to stimulate your interest in Partial Differential Equations through fundamental conceptual

building blocks in the study and application of Partial Differential Equations to practical problem solving.

Module 1 premises this course with the statement of the Essential Definitions to be found in the study of Partial Differential Equations and proceeds through First Order Equations, Quasi – Linear Equations and the Method of Lagrange. It is closed with a study of the Application of Partial Differential Equations to the Conservation Law which is developed to the concept of Shock – a consequence of an abrupt discontinuity.

Module 2 treats General First Order Equation with particular reference to Cauchy Method of Characteristic. It presents the three Types of Solution of Partial Differential Equations - Complete Solution (Integral), General Solution (Integral) and Singular Solution

Module 3 focuses on the higher order Partial Differential Equations commencing with the Second Order. This module Classifies Partial Differential Equations and lays emphasis on the Tricomi's Equation, its Characteristics and treats the Case of Two Independent Variables. It further proceeds to the Transformation of Independent Variables where three cases are highlighted; the Regular, the Hyperbolic and the Elliptic Cases.

Module 4 which closes the course takes on the Cauchy Problem and Characteristics Problem. It is partly occupied with the Fundamental Existence Theorem; the Cauchy Problem as well as the Cauchy Kovalevsky Theorem.

You will feel more at ease with Partial Differential Equations and life will never be the same again by the time you complete this course. In order to achieve this however, my advice is as follows:

- make sure that you have enough referential and study material available and at your disposal at all times
- devote sufficient quality time to your study.

I wish you luck.



**MAIN
COURSE**

CONTENTS		PAGE
Module 1	1
Unit 1	Definitions and Equations.....	1
Unit 2	Application of IVP Conservation Law, Development of Shock.....	19
Module 2	24
Unit 1	General First Order Equation and Cauchy Method of Characteristic.....	24
Unit 2	Types of Solution.....	32
Module 3	41
Unit 1	Second Order P.D.E. Classifications.....	41
Unit 2	Transformation of Independent Variables.....	49
Module 4	58
Unit 1	Cauchy Problem, Characteristics Problem and Fundamental Existence Theorem.....	58

MODULE 1

Unit 1	Definitions and Equations
Unit 2	Application of IVP Conservation Law, Development of Shock

UNIT 1 DEFINITIONS AND EQUATIONS**CONTENTS**

1.0	Introduction
2.0	Objectives
3.0	Main Content
3.1	Essential Definitions
3.2	First Order Equation
3.3	Quasi – Linear Equations
3.4	Method of Lagrange
4.0	Conclusion
5.0	Summary
6.0	Tutor-Marked Assignment
7.0	References/Further Reading

1.0 INTRODUCTION

What is a Partial Differential Equation, how do we classify Partial Differential Equations? How are they rendered graphically and how do we solve them? This unit addresses these questions with a tour of the basics of Partial Differential Equations; particularly on an introduction to the methods for deriving solution.

2.0 OBJECTIVES

At the end of this unit, you should be able to:

- define the term Partial Differential Equation
- classify First Order Equations
- investigate the methods for constructing solutions for Partial Differential Equations
- solve Quasi – Linear Equations
- explore the many definitions applied in deriving solutions
- apply the method of Lagrange in deriving solutions for Partial Differential Equations.

3.0 MAIN CONTENT

3.1 Essential Definitions

In some elementary course we encountered many physical problems that are modelled by ordinary differential equations and have learnt some of the basic solution technique for such equation. We shall now expand our view by examining Partial Differential Equations (P.D.E). Our Approach will deal with:

- i) Existence and Uniqueness of solutions.
- ii) Stability of solution to small perturbations.
- iii) Methods for constructing solutions.

We shall focus attention largely on (iii) although it is not always possible to solve a P.D.E in closed form.

0.1 Definition

A P.D.E
$$G\left(x, u, \frac{\partial u}{\partial x}, \frac{\partial^2 u}{\partial x^2}, \dots, \frac{\partial^m u}{\partial x_n^m}\right) = 0$$

Where $\underline{x} \in R^n$

$$\underline{x} = (x_1, x_2, \dots, x_n)$$

This is a relationship between a function U of several variables $\underline{x} = (x_1, x_2, \dots, x_n)$, $n \geq 2$ and its partial derivative.

0.2 Definition

By solution (0.1.0) in a domain $\Omega \subset R^n$ we mean a function $U = g(\underline{x})$ whose partial derivatives of order less than or equal to m (e m) exist in Ω and satisfy the equation. We note however that some P.D.E do not provide solution in the classical sense defined above.

Example:

$$x^2 \frac{\partial u}{\partial x} = 1$$

Does not have a solution in any domain, Ω that contain the origin, rather than a solution in the sense of distributions or generalised functions.

0.3 Definitions

A P.D.E is said to be of n th – order if the order of the highest partial derivation occurring in the equation and if the coefficient of the highest – order occur linearly the equation is said to be quasi – linear.

$$\sum_{i,j=1}^n A_{ij} \left(\underline{x}, u, \frac{\partial u}{\partial x}, \dots, \frac{\partial u}{\partial x^n} \right) \frac{\partial^2 u}{\partial x_i \partial x_j} + g \left(\underline{x}, u, \dots, \frac{\partial u}{\partial x^n} \right) = 0$$

It is quasi – linear and of 2nd order.

If the coefficient of the highest orders derivation are all functions of \underline{x} only. The age is said to be Semi Linear.

Example:

$$\sum_{i,j=1}^n A_{ij}(\underline{x}) \frac{\partial^2 u}{\partial x_i \partial x_j} + g \left(\underline{x}, u, \frac{\partial u}{\partial x}, \dots, \frac{\partial u}{\partial x^n} \right) = 0 \dots\dots\dots (0.3.1)$$

Is semi linear and of 2nd order.

The equation is linear if the coefficient of U and the coefficient of all its partial derivatives are functions of \underline{x} only.

E.g.
$$\sum_{ij=1}^n A_{ij}(\underline{x}) \frac{\partial^2 u}{\partial x_i \partial x_j} + \sum_{i=1}^n B_i(\underline{x}) \frac{\partial u}{\partial x_i} + c(\underline{x})U + g(\underline{x}) = 0 \dots\dots\dots (0.3.2)$$

It is linear and of 2nd order.

An equation that is not linear is said to be non-linear. A 2nd order e.g. (0.3.2) is said to be homogenous if g (x) is identically zero. Otherwise it is non – homogenous.

If (0.1.0) is a polynomial of degree k in the highest order partial derivation we say that the equation is of degree k.

$$\left(\frac{\partial u}{\partial x} \right)^2 + \left(\frac{\partial u}{\partial y} \right)^2 + \left(\frac{\partial u}{\partial z} \right)^2 = 1$$

It is 1st order non-linear degree 2.

In general any equation of degree k = 1 is non – linear.

Example:

$$1) \quad x \frac{\partial z}{\partial x} + y \frac{\partial z}{\partial y} = \cos xy$$

It is 1st order, linear non-homogenous.

$$2) \quad U \frac{\partial u}{\partial y} \frac{\partial^3 u}{\partial x^3} + \left(\frac{\partial^2}{\partial y^2} \right)^2 \sin u$$

It is 3rd order quasi – linear.

$$3) \quad \frac{\partial^2}{\partial xy} + \left(\frac{\partial u}{\partial x} \right)^2 = \frac{\partial y}{\partial z} + z^3$$

It is 2nd order and semi – linear.

$$4) \quad \frac{\partial^2 u}{\partial t^2} - c^2 \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right) = 0$$

It is 2nd order linear Homogenous.

$$5) \quad \left(\frac{\partial^2 u}{\partial x^2} \right)^3 + \left(\frac{\partial^2 u}{\partial y^2} \right) + \frac{\partial^2 u}{\partial x \partial y} + \frac{\partial u}{\partial y} = u$$

It is 2nd order non linear.

$$\begin{cases} U \frac{\partial v}{\partial x} + V \frac{\partial u}{\partial y} = x + y \\ V \frac{\partial v}{\partial x} + U \frac{\partial u}{\partial y} = x - y \end{cases}$$

System of 1st order quasi linear equation

$$(ax) z + (a)u_x + (a)Uz + (a) Vn + (av)Vz + Zx = ay = 0$$

Example: Given that

$$\begin{cases} u = g(x_i, y_i, z) \\ v = h(x_i, y_i, z) \end{cases} c^i(\Omega)$$

Determine the P.D.E of lowest order satisfied by the class of all functions defined implicitly by

$$G(u, v) = 0$$

Where, $G_u G_v \neq 0$ in Ω

3.2 First Order Equation

Examples of 1st order equations are:

$$Z x^2 + Z y^2 = 1$$

If $P = Zx, q = Zy$

$$P^2 + q^2 = 1$$

$$a(z) Zx + Zy = 0$$

$$a(z) p + q = 0$$

$$xZn + yZy = xZ (xp + yq = nZ)$$

3.3 Quasi-Linear Equations

This is given by

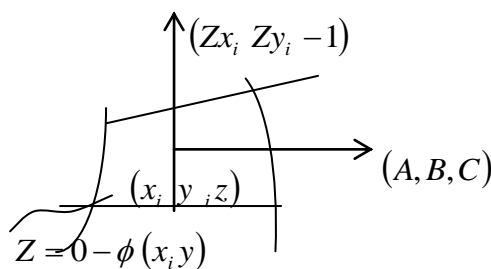
$$A(x, y, z) Zx + B(x, y, z) Zy = C(x, y, z) \dots\dots\dots (1.1.0)$$

Where, $(x, y) \in D \subset R^2$ and A, B, C are

$$C^0(\Omega), \Omega \text{ being in } R^3$$

Where projection on R^2 is 0

$$(1.1.0) \Rightarrow (Zx, Zy, -1) \text{ is perpendicular to } (A, B, C)$$



Implies that there exists an integral surface

$$\Sigma = \{ (x_i, y_i, z) : Z \phi (x_i, y) \}$$

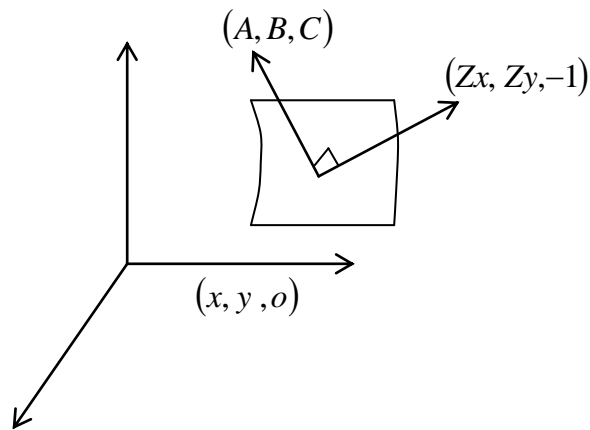
Passes thru (x_i, y_i, z) which is target to the given vector

$$A(x_i, y_i, z), B(x_i, y_i, z), C(x_i, y_i, z).$$

At the given point,

$$AZ_x + BZ_y = C$$

can be interpreted geometrically as a requirement that any surface $Z = Z(x, y)$ thru (x, y, z) must be tangent to a prescribed vector (A, B, C) .



The direction of the vector (A, B, C) is called the characteristics direction at the given point if (dx, dy, dz) lies in the tangent plane S at (x, y, z) then $(d_x, d_y, d_z)(Z_x, Z_y, -1) = 0$

$$\Rightarrow Z_x dx + Z_y dy = dz$$

Comparing the above result with (1.1.0)

We have that

$$\frac{dx}{A} = \frac{dy}{B} = \frac{dz}{C} \dots\dots\dots (1.1.1)$$

$$= \frac{dx}{dt} = A; \frac{dy}{dt} = B; \frac{dz}{dt} = C$$

$$= \frac{dy}{dx} = \frac{B}{A}; \frac{dz}{dx} = \frac{C}{A}.$$

Define (1.1.0) $A(x, y, z)Z_x + B(x, y, z)Z_y \pm C(x, y, z)$

By the characteristic of 1.1.0 we mean the integral curves of (1.1.1)

$$\text{char} = \frac{dx}{A} = \frac{dy}{B} = \frac{dz}{C}$$

Theorem 1.2

The integral curves of (1.1.1) generates the integral surface of (1.1.0)

$$A(x, y, z)Z_x + B(x, y, z)Z_y = C(x, y, z)$$

Proof

Let $Z = Z(x, y, z)$ be an integral of (1.1.0)

$$\text{Then } dz = Z_x dx + Z_y dy + Z_z dz \dots\dots\dots (1.2.0)$$

Suppose r is an integral curve of (1.1.1) then $dx = A dt$, $dy = B dt$ and $dz = C dt$

Substituting into (1.2.0) we have (1.1.0)

It can be proved that exactly one characteristic passes through each point of S . The general solution of 1.1.1 is of the form

$$y = y(x, \alpha, \beta)$$

$$z = z(x, \alpha, \beta)$$

Where α and β are arbitrary constant.

Solution for α and β we obtain

$$\alpha = u(x, y, z)$$

$$\beta = v(x, y, z)$$

Assuming that u and v are finally independent

$$\text{i.e. } \frac{\partial(u, v)}{\partial(x, y)}, \frac{\partial(u, v)}{\partial(x, z)}, \frac{\partial(u, v)}{\partial(y, z)}$$

are not all zero at any point (x, y, z) of S .

Definition 1.2

A single relation between u and v of the form

$$a(u, v) = 0$$

Is called the general solution of (1.1.0)

Examples:

Find the general solution of

$$xZ_x + yZ_y = Z$$

With characteristic equation

$$\frac{dx}{x} = \frac{dy}{y} = \frac{dz}{z}$$

$$\frac{dx}{x} = \frac{dy}{y}$$

$$\Rightarrow \ln y = \ln x + \ln x$$

$$\frac{y}{x} = x = u(x, y, z)$$

$$\text{Also } \frac{dz}{z} = \frac{dx}{x}$$

$$\ln Z = \ln x + \ln \beta$$

$$\frac{Z}{x} = \beta = v(x, y, z)$$

$$F(u, v) = 0$$

$$F(\alpha, \beta) = 0$$

$$F\left(\frac{y}{x}, \frac{z}{x}\right) = 0$$

$$\frac{z}{x} = F\left(\frac{y}{x}\right)$$

$$\Rightarrow Z = x F\left(\frac{y}{x}\right)$$

3.4 Method of Lagrange

This is a useful technique for integrating first order equation from algebra we have that is

$$\frac{a}{b} = \frac{c}{d}$$

Then the following relationship is true

$$\frac{K_1 a + K_2 c}{K_1 b + K_2 d} = \frac{a}{b} = \frac{c}{d}$$

For arbitrary values of the multiplies K_1 and K_2 so

$$\frac{dx}{A} = \frac{dy}{B} = \frac{dz}{C} = \frac{K_1 dx + K_2 dy + K_3 dz}{K_1 A + K_2 B + K_3 C} \quad \dots\dots\dots (1.2.1)$$

Hence equation more convenient for integration maybe found by appropriate choice of K_1, K_2, K_3 in (1.2.1)

Further examples:

Find the general solution of

i) $(y + 2xz)Zx - (x + 2yz)Zy = \frac{1}{2}(x^2 - y^2)$

$$x \in \mathbb{R}; y > 0$$

ii) $(z^2 - 2yz - y^2)Zx + (xy + xz)Zy - xy - xz$
 $G x^2 + y^2 + z^2 = 0$

Solution

$$x^2 + 4zy + 2z^2 \text{ where } K_1 = x$$

$$K_2 = z$$

$$K_3 = 2z + y$$

Characteristic equations are

$$\frac{dx}{y + 2xz} = \frac{dy}{x - 2yz} = \frac{dz}{\frac{1}{2}(x^2 - y^2)}$$

By method of langrage multiplier

$$\frac{1}{2} y d x + \frac{1}{2} x d y + dz = 0$$

$$\frac{1}{2} y x + \frac{1}{2} x y + z = \alpha$$

$$2 xy + 2 z = 2\alpha = \beta$$

$$\frac{1}{2} x d x + \frac{1}{2} y d y - 2 Z dz = 0$$

$$\frac{x^2}{4} + \frac{y^2}{4} - z^2 = \alpha$$

$$x^2 + y^2 - 4z^2 = \alpha$$

$$G(\alpha, \beta) = 0$$

$$G(x^2 + y^2 - 4z^2; xy + z) = 0$$

Initial value problem (or Cauchy problem in \mathbb{R}^2 consists of a determination of an integral surface S of (1.1.0) which passes through a pre-assigned space curve ξ . We noticed that those are the following possibilities:

- i) Unique surface.
- ii) Infinitely many surface.
- iii) No surface depending on the pre assigned curve ξ

Examples:

- 2) Consider the ivp

$$\begin{cases} yZx - xZy = 0 \\ \xi; Z(x,0) = x^4 \end{cases}$$

The characteristic equations are

$$\frac{dx}{y} = \frac{dy}{x} = \frac{dz}{0}$$

$$\frac{dx}{y} = \frac{dy}{-x}$$

$$-x dx = y dy$$

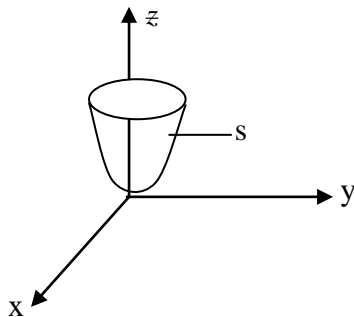
$$\frac{x^2}{2} + \frac{y^2}{2} = \alpha$$

$$x^2 + y^2 = \alpha$$

and

$$\begin{aligned}\frac{dx}{y} &= \frac{dz}{0} \\ dZ &= 0 \Rightarrow Z = \beta \\ F(\lambda, \beta) &= 0 \\ \beta &= F(\lambda) \\ Z &= F(x^2 + y^2)\end{aligned}$$

The general solution is any surface of revolution about z-axis



Given the curve $z = Z(x, 0) = F(x^2) = x^4$

$$\begin{aligned}\Rightarrow F(x) x^2 \\ \Rightarrow Z(x, y) = (x^2 + y^2)^2\end{aligned}$$

2) Consider the ivp

$$\begin{cases} yZx - xZy = 0 \\ \xi : \text{circle} \begin{cases} x^2 + y^2 = 1 \\ z = 1 \end{cases} \end{cases}$$

$$\begin{aligned}Z &= F(x^2 + y^2) \\ 1 &= F(x^2 + y^2) = 1 \\ \Rightarrow z &= F_1(x^2 + y^2) \text{ where } f_1 \text{ is any function which satisfies } f_1(1) = 1\end{aligned}$$

The solution exist but not unique.

These are certainly infinitely many such surfaces.

In this case ξ itself is a characteristic.

3) Consider the ivp

$$\begin{cases} yZx - xZy = 0 \\ \xi : \text{ellipse} \begin{cases} x^2 + y^2 = 1 \\ Z = y \end{cases} \end{cases}$$

$$\begin{aligned} Z &= F(x^2 + y^2) \\ \Rightarrow y &= F(x^2 + y^2) = F(1) \\ Z &= y, \text{ which is impossible.} \end{aligned}$$

∴ No such integral surface exists.

Theorem 1.8:

Let $AZ_x + BZ_y = C, (x, y, z) \in \Omega; \dots\dots\dots (1.8.0)$

$$\left. \begin{aligned} A, B, C \in C^0(\Omega) \text{ and } \xi: x = x_0(s) \\ y = y_0(s) \\ 0 \leq s \leq 1 \quad z = Z_0(s) \end{aligned} \right\} \dots\dots\dots (1.8.1)$$

A given space in $\Omega \ni$

$$x_0, y_0, z_0 \in C^1[0,1]$$

Let $Ay_0^1 - Bx_0^1 \neq 0 \dots\dots\dots (1.8.2)$

Then \exists a unique solution $z = z(x, y)$ of (1.8.0) defined in some neighbourhood of the given curve ξ and which satisfies the initial condition $Z(x_0^{(s)}, y_0^{(s)})$

$Z(x_0(s), y_0(s)) = Z_0(s) \dots\dots\dots (1.8.3)$

Proof:

Consider the characteristic system

$$\left. \begin{aligned} \frac{dx}{A} = \frac{dy}{B} = \frac{dz}{C} \\ \equiv \frac{dx}{dt} = A \\ \frac{dy}{dt} = B \\ \frac{dz}{dt} = C \end{aligned} \right\} \dots\dots\dots (1.8.4)$$

From the existence and uniqueness theorem for P.D.E we may solve (1.8.4) for a uniquely family of characteristics

$$\left. \begin{aligned} x &= x(x_0(s), y_0(s), z_0(s), t) \\ y &= y(x_0(s), y_0(s), z_0(s), t) \\ z &= z(x_0(s), y_0(s), z_0(s), t) \end{aligned} \right\} \in C^1[0,1] \quad \dots\dots\dots (1.8.5)$$

Such that

$$\left. \begin{aligned} x(s, 0) &= x_0(s) \\ y(s, 0) &= y_0(s) \\ z(s, 0) &= z_0(s) \end{aligned} \right\} \dots\dots\dots (1.8.6)$$

By hypothesis the Jacobian (J)

$$\begin{aligned} J &= \frac{\partial(x, y)}{\partial(st)} \Big|_{t=0} = \begin{vmatrix} x_s & x_t \\ y_s & y_t \end{vmatrix} \Big|_{t=0} = x_s y_t - x_t y_s \\ &= (B X_s - A y_s) \Big|_{t=0} \\ &= B X_0 - A y_0 \neq 0 \end{aligned}$$

∴ We can solve (1.8.5) uniquely for s and t in terms of x and y in the neighbourhood of the given curve

$$\begin{aligned} \xi : t &= 0 \\ s &= s(x, y) \\ t &= t(x, y) \end{aligned}$$

Substituting into (1.8.5) we have

$$\begin{aligned} Z &= (s(x, y), t(x, y)) = z(x, y) \\ &= \Phi(x, y) \end{aligned}$$

That $Z = \Phi(x, y)$ satisfies the initial conditions follows from $\Phi(x, y) \Big|_{t=0} = Z(s, 0) = Z_0(s)$

Φ satisfies the Partial Differential Equation for

$$\begin{aligned} &A \Phi_x + B \Phi_y \\ &= A (Z_s S_x + Z_t t_x) + B (Z_s S_y + Z_t t_y) \\ &= Z_s (A S_x + B S_y) + Z_t (A t_x + B t_y) \\ &= Z_s (s_x x_t + s_y y_t) + Z_t (t_x x_t + t_y y_t) \\ &= Z_s \frac{ds}{dt} + z_t \frac{dt}{dt} = Z_s(0) + Z_t(1) \\ &= Z_t = c \end{aligned}$$

Uniqueness follows from theorem (1.2). $AZ_n + BZ_y = C$

The integral curves of $\frac{dx}{A} = \frac{dy}{B} = \frac{dz}{C}$ generates the integral surface.

Summary: - Cauchy problem has a unique solution provided the initial curve is not characteristic.

Exercises:

1) Solve the following:

$$ZZx + Zy = 1$$

$$x = s$$

$$y = s$$

$$z = \frac{1}{2}s, 0 \leq s \leq 1$$

$$Zy + (Zx = 0, x \in R, y$$

$$2) \quad Z(x, 0) = \begin{cases} 1 - x^2, & |x| \leq 1 \\ 0, & |x| > 1 \end{cases}$$

$$Z(x, y) = F(x - cy) = 1 - (x - cy)^2 \text{ - unique solution}$$

$$Z(x, y) = F(n - cy) = 0 \quad \text{- intrnitty many}$$

Solution 2

We observed that $Ay_0^1 - Bx_0^1 =$

$$A = Z, B = 1$$

$$y_0^1(s) = 1, x_0^1 = 1$$

$$Ay_0^1 - Bx_0^1 = Z - 1 \neq 0 \text{ for } Z \neq 1$$

$$0 < \leq \in 1$$

Characteristic equation is

$$\frac{dx}{Z} = \frac{dy}{i} = \frac{dZ}{i}$$

So that we now have

$$\frac{dx}{y} = Z, \frac{dy}{-x} = 1, \frac{dz}{dt} = 1$$

$$\frac{dz}{dt} = 1 \Rightarrow Z = t + \lambda$$

$$Z(s_0) = \frac{s}{2} = \lambda$$

$$Z = t + \lambda = t + \frac{s}{2}$$

Similarly

$$y = t + \beta$$

$$y(s_0) = s = \beta$$

$$\Rightarrow y = t + s$$

$$\frac{dx}{dt} = Z = t + \frac{1}{2}s$$

$$x = \frac{t^2}{2} + \frac{1}{2}st + \alpha$$

$$S \quad s = \alpha$$

$$\begin{aligned} \Rightarrow x &= \frac{t^2}{2} + \frac{1}{2}st + s \\ &= \frac{1}{2}t(t+s) + s \\ &= \frac{1}{2}yt + s \end{aligned}$$

Write $t = y - s$ and substitute into x so that

$$\begin{aligned} X &= \frac{1}{2}y(y-s) + s \\ &= \frac{1}{2}y^2 - \frac{1}{2}ys + s \\ s &= x - \frac{1}{2}y^2 / 1 - \frac{y}{2} \\ s &= \frac{x - \frac{1}{2}y^2}{1 - \frac{y}{2}} \dots\dots\dots(i) \end{aligned}$$

Also write $s = y - t$ and substitute into

$$\begin{aligned} x &= \frac{1}{2}yt + y - t \\ t &= \frac{y-x}{1 - \frac{1}{2}} \dots\dots\dots(ii) \end{aligned}$$

Substitute (i) and (ii) in

$$\begin{aligned}
 Z &= t + \frac{1}{2} S \\
 Z &= \frac{y-x}{1-\frac{y}{2}} + \frac{1}{2} \left(\frac{x-y\frac{2}{2}}{1-\frac{y}{2}} \right) \\
 &= \frac{\frac{y^2}{2} - 2y - x}{y-2}.
 \end{aligned}$$

4.0 CONCLUSION

In this unit we have studied some basic and essential definitions of Partial Differential Equations; specifically those properties and general characteristics of First Order Equation, Quasi – Linear Equations and the utilisation of the Method of Lagrange in solving Partial Differential Equations.

We examined Partial Differential Equations from the perspectives of existence and uniqueness of solutions, stability of solution to small perturbations around the solution as well as the different methods for constructing solutions.

5.0 SUMMARY

Partial Differential Equations can be generically classified into families and methods of solution for classes categories based on their properties.

6.0 TUTOR-MARKED ASSIGNMENT

- Which of the following Partial Differential Equations is linear, quasi-linear or non-linear?

If P.D.E. is linear, state whether it is homogeneous equation or not.

- $u_{xx} + u_{yy} - 2u = x^2$
- $u_{xy} = u$
- $u u_x + x u_y = 0$
- $u_x^2 + \log u = 2xy$
- $u_{xx} - 2u_{xy} + u_{yy} = \cos x$
- $u_x(1 + u_y) = u_{xx}$
- $(\sin u_x)u_x + u_y = e^x$
- $2u_{xx} - 4u_{xy} + 2u_{yy} + 3u = 0$
- $u_x + u_x u_y - u_{xy} = 0$

2. Give the order of each of the following:

- a. $u_{xx} + u_{yy} = 0$
- b. $u_{xxx} + u_{xy} + a(x)u_y + \log u = f(x, y)$
- c. $u_{xxx} + u_{xyyy} + a(x)u_{xxy} + u^2 = f(x, y)$
- d. $u u_{xx} + u_{yy}^2 + e^u = 0$
- e. $u_x + cu_y = d$

3. Find the general solution of

$$u_{xy} + u_y = 0$$

4. Show that $u = F(xy) + x G\left(\frac{y}{x}\right)$

is a general solution of

$$x^2 u_{xx} - y^2 u_{yy} = 0$$

7.0 REFERENCES/FURTHER READING

- Adomian, G. (1994). *Solving Frontier Problems of Physics: The Decomposition Method*. Kluwer Academic Publishers.
- Courant, R. & Hilbert, D. (1962). *Methods of Mathematical Physics II*. New York: Wiley-Interscience.
- Evans, L. C. (1998). "Partial Differential Equations". Providence: *American Mathematical Society*.
- Jost, J. (2002). *Partial Differential Equations*. New York: Springer-Verlag.
- Petrovskii, I. G. (1967). *Partial Differential Equations*. Philadelphia: W. B. Saunders Co.
- Pinchover, Y. & Rubinstein, J. (2005). *An Introduction to Partial Differential Equations*. New York: Cambridge University Press.
- Polyanin, A. D. & Zaitsev, V. F. (2004). *Handbook of Non-linear Partial Differential Equations*. Boca Raton: Chapman & Hall/CRC Press.
- Polyanin, A. D. (2002). *Handbook of Linear Partial Differential Equations for Engineers and Scientists*. Boca Raton: Chapman & Hall/CRC Press.

Polyanin, A. D., Zaitsev, V. F. & Moussiaux, A. (2002). *Handbook of First Order Partial Differential Equations*. London: Taylor & Francis.

Wazwaz, Abdul-Majid (2009). *Partial Differential Equations and Solitary Waves Theory*. Higher Education Press.

UNIT 2 APPLICATION OF IVP CONSERVATION LAW, DEVELOPMENT OF SHOCK

CONTENTS

- 1.0 Introduction
- 2.0 Objectives
- 3.0 Main Content
 - 3.1 Application of IVP Conservation Law, Development of Shock
- 4.0 Conclusion
- 5.0 Summary
- 6.0 Tutor-Marked Assignment
- 7.0 References/Further Reading

1.0 INTRODUCTION

The characteristic equation for the single conservation law is derived and solved with the assumption of implicit function, discontinuity which implies shock is also demonstrated.

2.0 OBJECTIVES

At the end of this unit, you should be able to:

- state conservation law
- explain the concept of shock.

3.0 MAIN CONTENT

3.1 Application of IVP Conservation Law, Development of Shock

The conservation law states that rate of change of total substance contained in a fixed (arbitrary) domain Ω is equal to the flux of that substance across the boundary $\partial\Omega$.

Let U be the density of the substance and F = flux, then the conservation

law is given by rate of flow $\frac{d}{dt} \int_{\Omega} u dx = - \int_{\partial\Omega} \underline{F} \cdot \underline{n} ds$

$$\Rightarrow \int_{\Omega} \frac{\partial}{\partial t} u dx = \int_{\Omega} U_t dx + \int_{\partial\Omega} \underline{F} \cdot \underline{n} ds = 0$$

$$\int_{\Omega} u_t dx + - \int_{\Omega} \text{div } F dx = 0$$

$$\int_{\Omega} (ut + \operatorname{div} f) dx = 0 \quad \text{_____} (i)$$

$$ut + \operatorname{div} f = 0$$

Single conservation law

$$ut + \underline{f}_x = 0$$

$$\Rightarrow ut + a(u)ux = 0 \quad \text{_____} (ii)$$

Characteristic equation

$$\frac{dt}{1} = \frac{dx}{a(u)} = \frac{du}{0}$$

$$\frac{du}{0} = \frac{dt}{1}$$

$$\Rightarrow U = \text{constant along } \frac{du}{dt} = a(u)$$

i.e. on the characteristic $x = x(t)$ which propagates with speed a
 u is a constant
 a = signal of the speed.

Solve the following IVP

i) $ut + a(u)ux = 0$

$$u(x, 0) = f(x)$$

$$\frac{dt}{1} = \frac{dx}{a(u)} = \frac{du}{0}$$

$$\Rightarrow u = \alpha$$

$$\frac{dx}{dt} = a(u) = a(\alpha)$$

$$x = at + \beta$$

General solution $F(\alpha, \beta) = 0$

$$F(u, x - a(u)t) = 0$$

$$\Rightarrow u = F(x - a(u)t)$$

\Rightarrow Solution is implicitly defined by

$$u = F(x - a(u)t)$$

$$U_t - F_u U_t = -u = x - a(u)t$$

$$= F^1(-a(u)) - u = x - a(u)t$$

$$(1 + F^1 a^1 t) u_t = -f^1 a(u)$$

$$\Rightarrow U_t = \frac{a(u) f^1}{1 + a^1 f^1 t}$$

$$U_x = F'(1 - a^1 u_x t)$$

$$U_x = \frac{f^1}{1 + a^1 f^{1t}} \quad \text{Assuming implicit function theorem}$$

Therefore U given implicitly satisfies the P.D.E provided

$$1 + a^1 f^{1t} \neq 0. \text{ if } 1 + a^1 f^{1t} = 0$$

U_t, U_x will become infinite and shock is said to be developed i.e.

a discontinuity exist in Ω . If:

- 1) a is constant, no shock $\forall t \geq 0$
- 2) F is constant, no shock $\forall t \geq 0$
- 3) a, f, both non – deterring or non-increasing

For non – decreasing $f^1 \geq 0$

For non – increasing $f^1 \leq 0$

$a^1 f^1 \geq 0$, no - shock $\lambda \in \geq 0$

Exercises:

1. Find a solution of $Z_x + Z_y = 0$

$$Z(x, 0) = x$$

Draw the lines in the $x - y$ plane, along where solution is constant. Do shocks ever developed for $y \geq 0$?

2. $Z^2_x + Z_y = 0$

$$Z(x, 0) = x$$

$$\text{Derive the solution } Z(x, y) = \begin{cases} x & \text{when } y = 0 \\ \sqrt{\frac{1+4xy}{2y}} - 1 & y \neq 0 \\ & 1+4xy > 0 \end{cases}$$

Do shocks ever developed? Show that

$$\lim_{y \rightarrow 0} Z(x, y) = x$$

$$y \rightarrow 0$$

$$\frac{dx}{z} = \frac{dy}{1} = \frac{dz}{0}$$

$$\Rightarrow Z = \alpha \quad dx = z dy$$

$$x = zy + \beta$$

$$z(x, 0) = \beta = x$$

$$= z y + x = z$$

$$z = \frac{x}{1-y}$$

The solution is constant along the lines

$$y = 0, y > 0, y \leq -1$$

$$zx = \frac{x}{(1-y)^2}$$

Shock develop for $y = 1$.

4.0 CONCLUSION

This unit has practically exposed us to the real world application of Partial Differential Equations through a scenario involving conservation law where we determine shock.

5.0 SUMMARY

The law of conservation states that the rate of change of total substance contained in a fixed domain is equal to the flux of that substance across the domain boundary.

6.0 TUTOR-MARKED ASSIGNMENT

1. Derive the telegraph equation

$$u_{tt} + au_t + bu = c^2 u_{xx}$$

by considering the vibration of a string under a damping force proportional to the velocity and a restoring force proportional to the displacement.

2. Use Kirchhoff's law to show that the current and potential in a wire satisfy

$$\begin{aligned} i_x + C v_t + Gv &= 0 \\ v_x + L i_t + Ri &= 0 \end{aligned}$$

where i = current, $v = L =$ inductance potential, C = capacitance, G = leakage conductance, R = resistance

7.0 REFERENCES/FURTHER READING

Adomian, G. (1994). *Solving Frontier Problems of Physics: The Decomposition Method*. Kluwer Academic Publishers.

Courant, R. & Hilbert, D. (1962). *Methods of Mathematical Physics II*. New York: Wiley-Interscience.

Evans, L. C. (1998). "Partial Differential Equations." Providence: *American Mathematical Society*.

- Jost, J. (2002). *Partial Differential Equations*. New York: Springer-Verlag.
- Petrovskii, I. G. (1967). *Partial Differential Equations*. Philadelphia: W. B. Saunders Co.
- Pinchover, Y. & Rubinstein, J. (2005). *An Introduction to Partial Differential Equations*. New York: Cambridge University Press.
- Polyanin, A. D. & Zaitsev, V. F. (2004). *Handbook of Non-linear Partial Differential Equations*. Boca Raton: Chapman & Hall/CRC Press.
- Polyanin, A. D. (2002). *Handbook of Linear Partial Differential Equations for Engineers and Scientist*. Boca Raton: Chapman & Hall/CRC Press.
- Polyanin, A. D., Zaitsev, V. F. & Moussiaux, A. (2002). *Handbook of First Order Partial Differential Equations*. London: Taylor & Francis.
- Wazwaz, Abdul-Majid (2009). *Partial Differential Equations and Solitary Waves Theory*. Higher Education Press.

MODULE 2

Unit 1	General First Order Equation and Cauchy Method of Characteristic
Unit 2	Types of Solution

UNIT 1 GENERAL FIRST ORDER EQUATION AND CAUCHY METHOD OF CHARACTERISTIC**CONTENTS**

1.0	Introduction
2.0	Objectives
3.0	Main Content
	3.1 General First Order Equation
	3.2 Cauchy Method of Characteristic
4.0	Conclusion
5.0	Summary
6.0	Tutor-Marked Assignment
7.0	References/Further Reading

1.0 INTRODUCTION

General non – linear first order partial differential equations have a form $F(x,y,z,p,q) = 0$ where $p = Z_x$ and $q = z_y$ whose solution lead to the concept of the Monge cone and the chain curve stripe.

2.0 OBJECTIVES

At the end of this unit, you should be able to:

- use General non – linear First Order Equation to solve some problems
- sketch and explain the Monge cone
- apply Cauchy Method of Characteristic equations

3.0 MAIN CONTENT**3.1 General First Order Equation**

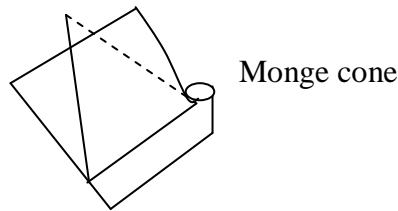
The general non – linear P.D.E of 1st order has the form

$$F(x,y,z,p,q) = 0 \quad \dots\dots\dots (1.9.1)$$

Where $p = Z_x$ and $q = z_y$

At each point $p(x, y, z)$ on an integral surface $z = z(x, y)$ the direction number $(p, q, -1)$ of the normal to the surface are related through equation (1.9.1)

The P.D.E will restrict its solution to these surface having tangent planes belonging to a 1-parameter family $q = G(x, y, z, p)$. Generally this one – parameter family of planes envelope a cone called the Monge cone.

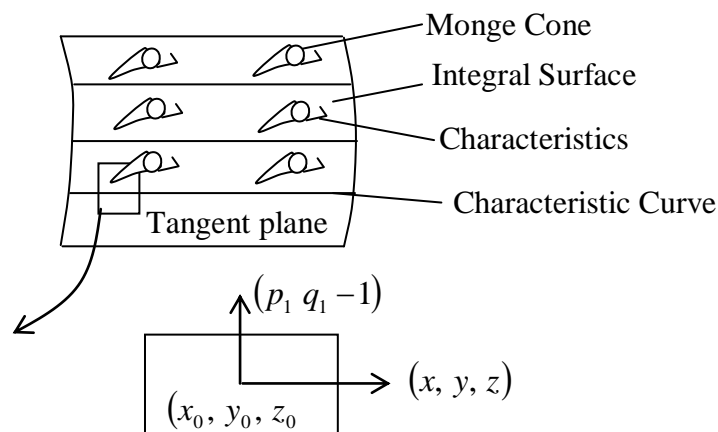


The geometrical significance of the 1st order P.D.E in (1.9.1) is that any solution surface through a point in space must be tangent to the corresponding Monge cone

3.2 Cauchy Method of Characteristic

Let $z = z(x, y) \in C^2$ be a given integral surface. At each point the surface will be tangent to the Monge cone

Furthermore, the lines of contacts between the tangent planes of the surfaces and the cones define a field of directions on the surface called characteristic direction. These integral curves of field define a family of characteristic curves.



The Monge cone at a fix point (x_o, y_o, z_o) in the envelope of one particular family of planes.

$$\left. \begin{aligned} z - z_0 &= p(x - x_0) + q(y - y_0) \\ \text{where } F(x_0, y_0, z_0, p, q) &= 0 \\ \text{or } q &= q(x_0, y_0, z_0, p) \end{aligned} \right\} \dots\dots\dots (1.10.1)$$

It's thus given by

$$\left. \begin{aligned} \tilde{z} - z_0 &= \tilde{p}(x - x_0) + q(x_0, y_0, z_0, p)(y - y_0) \\ o &= x - x_0 + \frac{dq}{dp}(y - y_0) \end{aligned} \right\} \dots\dots\dots (1.10.2)$$

Where p is adopted as the parameter using (1.10.1) we have

$$\frac{df}{dp} = Fp + Fq \frac{dq}{dp} = 0 \dots\dots\dots (1.10.3)$$

Eliminating $\frac{dq}{dp}$ from (1.10.2) yields the Hg

Equation for the Monge cone

$$\left. \begin{aligned} F(x_0, y_0, Z_0, p, q) &= 0 \\ z - z_0 &= p(x - x_0) + q(y - y_0) \\ \frac{x - x_0}{Fp} &= \frac{y - y_0}{Fq} \end{aligned} \right\} \dots\dots\dots (1.10.4)$$

Eliminating p and q from (1.10.4) yield a more standard form of the equation of the cone.

If given p and q the last two equation of (1.10.4) define the line of contact between the cone and the tangent plane.

It may be written in the form

$$\left. \begin{aligned} u &= g(x_i, y_i, z_i) \\ v &= h(x_i, y_i, z_i) \end{aligned} \right\} c^i(\Omega)$$

The characteristic direction is

$$(Fp, Fq, pFp + qFq) \dots\dots\dots (1.10.6)$$

If therefore follows that the characteristics curves are determined by the O.D.E

$$\frac{dx}{Fp} = \frac{dy}{Fq} = \frac{dz}{pFp + qFq}$$

$$\equiv \frac{dx}{dt} = Fq, \frac{dy}{dt} = Fq, \frac{dz}{dt} = pFp + q Fq \quad \dots\dots\dots (1.10.7)$$

Assuming that the integral surface is yet unknown, the 3 equations in (1.10.9) are not sufficient to determine the characteristic curve comprising the surface.

This is because the equation contains 2 addition unknown p and q.

However, along a characteristic curve on the given integral surface we have

$$\left. \begin{aligned} \frac{dp}{dt} &= p_x x_t + p_y y_t = p_x f_p + p_y f_q \\ \frac{dq}{dt} &= q_x x_t + q_y y_t = q_x f_p + q_y f_q \end{aligned} \right\} \quad \dots\dots\dots (1.10.8)$$

Differentiating the given Partial Differential Equation in (1.9.1), we have

$$\begin{aligned} F_x + Fp p_x + Fq q_x &= 0 \\ F_y + Fz q + Fp p_y + Fq q_y &= 0 \end{aligned}$$

But $q_x = \frac{\partial Z^2}{\partial x \partial y} \quad (z = c^2)$

So

$$\begin{aligned} F_x + Fz p + (Fp p_x + Fq p_y) &= 0 \\ F_y + Fz q + (Fp q_x + Fq q_y) &= 0 \end{aligned}$$

(1.10.8) then yields

$$\left. \begin{aligned} \frac{dp}{dt} &= - Fx - pFz \\ \frac{dq}{dt} &= - Fy - qFz \end{aligned} \right\} \quad \dots\dots\dots (1.10.9)$$

The 5 equations in 1.10.7 and 1.10.9 are called the characteristics equation associated with the Partial Differential Equation. The situation is now more complicated than in (1.9.1). All together we have 6 equations.

$$\begin{aligned} F(x, y, z, p, q) &= 0 \\ \frac{dx}{dt} &= Fp, \frac{dy}{dt} = Fq \end{aligned}$$

$$\begin{aligned} \frac{dt}{dt} &= - (Fx + pFz) \\ \frac{dq}{dt} &= (Fy + qFz) \\ &\equiv F(x, y, z, p, q) = 0 \\ \frac{dx}{Fp} &= \frac{dy}{Fq} = \frac{dz}{pFp + qFq} \\ &= \frac{dp}{-[Fx + pFz]} = \frac{dq}{-[Fy + qFz]} \end{aligned}$$

For the 5 – unknown functions

$$x(t), y(t), z(t), p(t), q(t)$$

In other words if $F(x, y, z, p, q) = 0$ is satisfied at an initial point say x_0, y_0, z_0, p_0, q_0 for $t = 0$. The 5 characteristic equations in (1.10.7), (1.10.9) will determine a unique solution $x(t), y(t), z(t), p(t), q(t)$, passing through the x point and along which $f = 0$ will be satisfied for all t.

Theorem 1.11

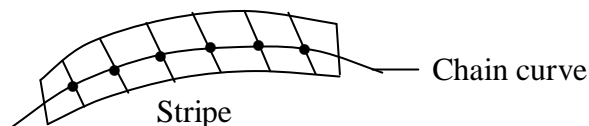
Along any solution of characteristic equation of (1.10.10) $F(x, y, z, p, q) = 0$

Proof

Exercises:

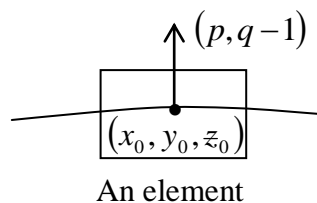
Defined 1.12

A ship is defined as a space curve $x = x(t)$ $y = y(t)$ and $z = z(t)$ in addition to the family of tangent planes with $(p, q, -1)$ as normal.



Defined 1.13

An element of a stripe is defined as a point on a characteristic curve including the corresponding tangent plane at that point.



Remark

Note that not any set of 5 functions can be interpreted as a strip. The planes must be tangent to the curve which is that conditions that

$$\frac{dz}{dt} = p \frac{dx}{dt} + q \frac{dy}{dt}$$

Theorem 1.14

If a characteristic strip $x(t), y(t), z(t), p(t), q(t)$ has x_0, y_0, z_0, p_0, q_0 in common with an integral surface $z = u(x, y)$ then it lies completely on that surface.

Theorem 1.15

Given $F(x, y, z, p, q) = 0$ (1.9.1)

And suppose along the initial curve

$x = x_0(s), y = y_0(s), 0 \leq s \leq 1$, the initial values $z = z_0(s)$ are assigned and $x_0, y_0, z_0 \in C^2[0,1]$ have been determined satisfying

$$F(x_0(s), y_0(s), z_0(s), p_0(s), q_0(s)) = 0 \text{ and}$$

$$\frac{dz_0}{ds} = p_0 \frac{dx_0}{ds} + q_0 \frac{dy_0}{ds} \text{ with}$$

$$\frac{dx_0}{ds} f_q(x_0, y_0, z_0, p_0, q_0) - \frac{dy_0}{ds} f_p(x_0, y_0, z_0, p_0, q_0) \neq 0$$

then in the same neighbourhood of the initial curve, there exists a unique solution $z = z(x, y)$ of (1.9.1) containing the initial strip that is such that.

$$z(x_0(s), y_0(s)) = z_0(s)$$

$$z_x(x_0(s), y_0(s)) = p_0(s)$$

$$z_y(x_0(s), y_0(s)) = q_0(s)$$

4.0 CONCLUSION

Solution for general non – linear Partial Differential Equations of 1st order has a geometrical significance in relation to the Monge cone.

5.0 SUMMARY

The form of the general non – linear first order Partial Differential Equation is $F(x,y,z,p,q) = 0$ where any solution surface through a point in space must be tangent at that point to the corresponding Monge cone.

6.0 TUTOR-MARKED ASSIGNMENT

1. Solve
$$\frac{\partial w}{\partial t} - 3\frac{\partial w}{\partial x} = 0$$

subject to
$$w(x, 0) = \sin x$$

2. Solve the following equation using the method of characteristics

a.
$$\frac{\partial u}{\partial t} + c\frac{\partial u}{\partial x} = e^{2x} \quad \text{subject to } u(x, 0) = f(x)$$

b.
$$\frac{\partial u}{\partial t} + x\frac{\partial u}{\partial x} = 1 \quad \text{subject to } u(x, 0) = f(x)$$

c.
$$\frac{\partial u}{\partial t} + 3t\frac{\partial u}{\partial x} = u \quad \text{subject to } u(x, 0) = f(x)$$

d.
$$\frac{\partial u}{\partial t} - 2\frac{\partial u}{\partial x} = e^{2x} \quad \text{subject to } u(x, 0) = \cos x$$

e.
$$\frac{\partial u}{\partial t} - t^2\frac{\partial u}{\partial x} = -|u| \quad \text{subject to } u(x, 0) = 3e^x$$

3. Show that the characteristics of

$$\frac{\partial u}{\partial t} + 2u\frac{\partial u}{\partial x} = 0$$

$$u(x, 0) = f(x)$$

are straight lines

4. Take a look at the problem

$$\frac{\partial u}{\partial t} + 2u\frac{\partial u}{\partial x} = 0$$

$$u(x, 0) = f(x) = \begin{cases} 1 & x < 0 \\ 1 + \frac{x}{L} & 0 < x < L \\ 2 & L < x \end{cases}$$

a. Determine equations for the characteristics

b. Determine the solution $u(x, t)$

- c. Sketch the characteristic curves.
- d. Sketch the solution $u(x, t)$ for fixed t .

7.0 REFERENCES/FURTHER READING

- Adomian, G. (1994). *Solving Frontier Problems of Physics: The Decomposition Method*. Kluwer Academic Publishers.
- Courant, R. & Hilbert, D. (1962). *Methods of Mathematical Physics II*. New York: Wiley-Interscience.
- Evans, L. C. (1998). "Partial Differential Equations." Providence: *American Mathematical Society*.
- Jost, J. (2002). *Partial Differential Equations*. New York: Springer-Verlag.
- Petrovskii, I. G. (1967). *Partial Differential Equations*. Philadelphia: W. B. Saunders Co.
- Pinchover, Y. & Rubinstein, J. (2005). *An Introduction to Partial Differential Equations*. New York: Cambridge University Press.
- Polyanin, A. D. & Zaitsev, V. F. (2004). *Handbook of Non-linear Partial Differential Equations*. Boca Raton: Chapman & Hall/CRC Press.
- Polyanin, A. D. (2002). *Handbook of Linear Partial Differential Equations for Engineers and Scientists*. Boca Raton: Chapman & Hall/CRC Press.
- Polyanin, A. D., Zaitsev, V. F. & Moussiaux, A. (2002). *Handbook of First Order Partial Differential Equations*. London: Taylor & Francis.
- Wazwaz, Abdul-Majid (2009). *Partial Differential Equations and Solitary Waves Theory*. Higher Education Press.

UNIT 2 TYPES OF SOLUTION

CONTENTS

- 1.0 Introduction
- 2.0 Objectives
- 3.0 Main Content
 - 3.1 Types of Solution
 - 3.1.1 Complete Solution (Integral)
 - 3.1.2 General Solution (Integral)
 - 3.1.3 Singular Solution
- 4.0 Conclusion
- 5.0 Summary
- 6.0 Tutor-Marked Assignment
- 7.0 References/Further Reading

1.0 INTRODUCTION

Partial Differential Equations can have three types of solutions; the complete solution, the general solution and the singular solution. All are treated in this unit.

2.0 OBJECTIVES

At the end of this unit, you should be able to:

- categorise the different types of solution of partial differential equations
- describe the methods used in deriving complete solution
- explain what a general solution is
- explain why some Partial Differential Equations are singular solutions.

3.0 MAIN CONTENT

3.1 Types of Solution

We observed that the general solution of the 1st order P.D.E (1.9.1) is an expression involving an arbitrary function of one variable. This naturally is the extension of the result that the general solution of an order of first order involves one arbitrary constant.

3.1.1 Complete Solution (Integral)

Any solution of the form

$$Z = \Phi(x, y, a, b) \dots\dots\dots (1.16.1)$$

Where a and b are arbitrary parameters represent two parameter family of surfaces. No systematic rule determining the complete integral is available. The complete integral is significant in the sense that the envelope of any family of solution of the 1st order equation (1.1.1) depending on some parameter is again a solution. Indeed equation 1.9.1 defines the tangent plane of a solution. If a surface has the same tangent plane as a solution at some point in space, then it also satisfies the equation there. The envelope of a family of solutions is also a solution since it is in contact at each of its points with one of these earlier mentioned solutions.

3.1.2 General Solution (Integral)

The general solution of 1.9.1 can thus be obtained from the complete integral if we prescribe the 2nd parameter b, say $b = b(a)$ as an arbitrary function of a. The enveloped of the one parameter subsystem of the complete integral is then considered as follows

$$Z = \Phi(x, y, a, b(a)) \dots\dots\dots (1.16.1)$$

Differentiating with respect to (wrt) a, we have

$$0 = \Phi_a(x, y, a, b(a)) + \Phi_b(x, y, a, b(a)) \frac{db}{da} \dots\dots\dots (1.16.2)$$

Eliminating (a) between 1.16.1 and 1.16.2 yield a single expression (involving the arbitrary function b(a) which is the general solution of (1.9.1)

3.1.3 Singular Solution

This is the envelope of the full two parameter family of surfaces defined by the complete solution and is given by the 3 relation

$$\begin{aligned} Z &= \Phi(x, y, a, b) \\ 0 &= \Phi_a(x, y, a, b) \\ 0 &= \Phi_b(x, y, a, b) \end{aligned}$$

Examples**Type I**

$$F(p, q) = 0$$

$$\text{Solve } p^2 - q^2 = 1$$

$$\text{Write } f(p, q) = p^2 - q^2 - 1 = 0$$

$$F(a, h(a)) = a^2 - (h(a))^2 - 1 \text{ and}$$

$$h(a) = (a^2 - 1)^{1/2}$$

A complete solution is

$$Z = ax + (a^2 - 1)^{1/2} y + c$$

$$Z = ax + by + c$$

Put $b = (a^2 - 1)^{1/2}$ and diff with a to get

$$O = x + \frac{ay}{(a^2 - 1)^{1/2}}$$

$$\frac{-x}{y} = \frac{a}{(a^2 - 1)^{1/2}}$$

General solution is

$$\frac{Z}{a} = x + \left(\frac{y}{x}\right) y + \frac{c}{a}$$

$$\alpha x z = x^2 - y^2 + \alpha x \quad (\alpha = 1/a)$$

$$\alpha x (z - 1) = x^2 - y^2$$

There are singular solutions since

$$z = a x + b y + c$$

$$o = x + \frac{ay}{(a^2 - 1)^{1/2}}$$

$$O = 1$$

Example:

$$\text{Consider } p^2 + q^2 = 1$$

$$\text{Recall } f(x, y, z, p, q) = o$$

$$p^2 + q^2 - 1 = o$$

$$\text{By } \frac{dx}{fp} = \frac{dy}{fq} = \frac{dz}{pf_p + qf_q} = \frac{dp}{-(fx + pfz)} = \frac{dq}{-(fy + qfz)}$$

$$fx = 0, fy = 0, fz = 0, fp = 2p, fq = 2q$$

$$\frac{dx}{2p} = \frac{dy}{2q} = \frac{dz}{2(p^2 + q^2)} = \frac{dp}{0} = \frac{dq}{0}$$

$$dp = 0$$

$$p = a \text{ (a is constant)}$$

$$q^2 = 1 - a^2$$

$$q = (1 - a^2)^{\frac{1}{2}}$$

$$p = zx = \frac{\partial z}{\partial y} = (1 - a^2)^{\frac{1}{2}}$$

$$dz = \frac{\partial z}{\partial x} dx + \frac{\partial z}{\partial y} dy$$

$$\int dz = \int a dx + \int (1 - a^2)^{\frac{1}{2}} dy$$

$$z = ax + (1 - a^2)^{\frac{1}{2}} y + b$$

General solution is given by

$$z = ax + \sqrt{1 - a^2} y + \Phi(a)$$

Differentiating wrt a we have

$$0 = x - \frac{a}{\sqrt{1 - a^2}} y + \Phi'(a)$$

Singular solution: None

$$\text{Since } z = ax + \sqrt{1 - a^2} y + b$$

Differentiating wrt a

$$za = 0 = x - \frac{a}{\sqrt{1 - a^2}}$$

$$zb = 0 = \sqrt{1 - a^2}$$

Examples:

Given $xp + yq = pq$, Find

1. The initial element if $x = x_0$, $y = 0$ and $z = \frac{x_0}{2}$ $z(x, 0) = \frac{x}{2}$
2. The characteristics stripe containing the initial elements
3. The integral surface which contain the initial element.

Solution

$$xp + yq = pq$$

$$xp + yq - pq = 0$$

$$f(x, y, z, p, q) = 0$$

$$(x_0, 0, \frac{1}{2}x_0, p_0, q_0) \text{ assume}$$

$$x_0 p_0 = p_0 q_0$$

$$\Rightarrow x_0 = q_0$$

According to the strip condition

$$dz = \frac{\partial z}{\partial x} dx + \frac{\partial z}{\partial y} dy$$

$$\frac{\partial z_0}{\partial x_0} = \frac{\partial z_0}{\partial x_0} + \frac{\partial z}{\partial y} \frac{\partial y}{\partial x}$$

$$\frac{1}{2} = p_0$$

Initial element is $(x_0, 0, \frac{1}{2}x_0, \frac{1}{2}, x_0)$

For simplicity let us take $x_0 = 1$

For the characteristic equation $\frac{dx}{fp} = \frac{dy}{fq} = \frac{dz}{pfp + qfq} = \frac{dp}{-(fx + pfz)} = \frac{dq}{-(fy + qfz)}$

$$\frac{dx}{dt} = x - q \quad \frac{dq}{dt} = -q$$

$$\frac{dp}{dt} = -p \quad \frac{dz}{dt} = -pq$$

$$\frac{dy}{dt} = y - p$$

Integrating we obtain

$$x = x_0 \cosh t$$

$$y = \frac{1}{2} \sinh t$$

$$z = \frac{1}{4} x_0 (e^{-2t} + 1)$$

$$p = \frac{1}{2} e^{-t}$$

$$q = x_0 e^{-t}$$

Eliminating x_0 and t from above, we obtain

$$8xyz + x^2 = 4z^2$$

Exercise

Solve

- 1) $pq = u$ with $u(o, s) = s^2$
- 2) determine the integral surface of $xpq + yq^2 = 1$ which contain the curve $z = x, y = o$

Earlier Example

$$\begin{aligned}
 p^2 - q^2 &= 1 \\
 f(x, y, z, p, q) &= p^2 - q^2 - 1 \\
 f_x = 0, f_y = 0, f_z &= 0, f_p = 2p, f_q = 2q \\
 \frac{dx}{f_p}, \frac{dy}{f_q} &= \frac{dz}{p f_p + q f_q} = \frac{dp}{-(f_x + p f_z)} = \frac{dq}{-(f_y + q f_z)} \\
 \frac{dx}{2p}, \frac{dy}{-2q} &= \frac{dz}{2p^2 - 2q^2} = \frac{dp}{o} = \frac{dq}{o} \\
 p &= a \\
 q^2 &= p^2 - 1 \\
 q^2 &= (a^2 - 1) \\
 q &= \sqrt{a^2 - 1} \\
 dz &= \frac{\partial z}{\partial x} dx + \frac{\partial z}{\partial y} dy \\
 dz &= a dx + \sqrt{a^2 - 1} dy \\
 z &= ax + \sqrt{a^2 - 1} y + c
 \end{aligned}$$

Put

$$\begin{aligned}
 b &= (a^2 - 1)^{\frac{1}{2}} \text{ and diff wrt } a \\
 o &= x + \frac{ay}{(a^2 - 1)^{\frac{1}{2}}} \\
 \frac{-x}{y} &= \frac{a}{(a^2 - 1)^{\frac{1}{2}}}
 \end{aligned}$$

General solution is

$$\frac{z}{a} = x + \left(\frac{-y}{x} \right) y + c/a$$

We can rewrite it as

$$\alpha x z = x^2 - y^2 + \alpha c x \quad \left(\alpha = \frac{1}{a}\right)$$

$$\alpha x z - \alpha c x = x^2 - y^2$$

$$\alpha x (z - c) - x^2 - y^2$$

There is no singular solution

$$z = ax + by + c$$

$$\left. \begin{array}{l} o = x + \frac{a}{(a^2 - 1)^{1/2}} y \text{ wrt } a \\ o = y \text{ wrt } b \end{array} \right\} \text{are not consistent}$$

Exercise:

Find the complete and singular solution of

$$p^2 + q^2 = 9$$

TYPE II

Consider $z = px + qy + f(p, q)$

Solution

Using the characteristic equation

$$i.e. \frac{dx}{fp} = \frac{dy}{fq} = \frac{dz}{pfp + qfq} = \frac{dp}{-(fx + pfz)} = \frac{dq}{-(fy + qf)}$$

Then

$$f(x, y, z, p, q) = z - px - qy - f(p, q) = 0$$

$$fx = -p \quad fy = -q$$

$$fz = 1 \quad fp = -x \quad fq = -(x + fp)$$

$$fq = -(y + fq)$$

Then

$$\frac{dx}{-(x + fp)} = \frac{dy}{-(y + fq)} = \frac{dz}{-p(x + fp) - q(y + fq)}$$

$$= -\frac{dp}{o} = -\frac{dq}{o}$$

$$\left. \begin{array}{l} dp = o \Rightarrow p = a \\ dq = o \Rightarrow q = b \end{array} \right\} \text{constant}$$

Complete solution b

$$z = ax + by + f(a, b)$$

Exercise:

Solve $(p + q)(z - xp - yq) = 1$

Find the complete solution

$$z = xp + yp - \frac{1}{(prq)}$$

$$\text{Solve } 4(1 + z^3) = 9z^4 pq$$

$$\frac{4 + 4z^3}{qz^4} = pq$$

$$\frac{4}{q} z^{-4} + \frac{4}{q} z^{-1} - pq = 0$$

4.0 CONCLUSION

General solution of First Order Partial Differential Equations results in an expression involving an arbitrary function of one variable.

5.0 SUMMARY

The different types of solution of Partial Differential Equations are categorised into complete solution, general solution and singular solution.

6.0 TUTOR-MARKED ASSIGNMENT

1. Determine the general solution of

a. $u_{xx} - \frac{1}{c^2}u_{yy} = 0$ $c = \text{constant}$

b. $u_{xx} - 3u_{xy} + 2u_{yy} = 0$

c. $u_{xx} + u_{xy} = 0$

d. $u_{xx} + 10u_{xy} + 9u_{yy} = y$

$$u_{xx} = au_t + bu_x - \frac{b^2}{4}u + d$$

2. Show that
is parabolic for a, b, d constants.

7.0 REFERENCES/FURTHER READING

- Adomian, G. (1994). *Solving Frontier Problems of Physics: The Decomposition Method*. Kluwer Academic Publishers.
- Courant, R. & Hilbert, D. (1962) *Methods of Mathematical Physics II*. New York: Wiley-Interscience.
- Evans, L. C. (1998). “Partial Differential Equations”. Providence: *American Mathematical Society*.
- Jost, J. (2002). *Partial Differential Equations*. New York: Springer-Verlag.
- Petrovskii, I. G. (1967). *Partial Differential Equations*. Philadelphia: W. B. Saunders Co.
- Pinchover, Y. & Rubinstein, J. (2005). *An Introduction to Partial Differential Equations*. New York: Cambridge University Press.
- Polyanin, A. D. & Zaitsev, V. F. (2004). *Handbook of Non-linear Partial Differential Equations*. Boca Raton: Chapman & Hall/CRC Press.
- Polyanin, A. D. (2002). *Handbook of Linear Partial Differential Equations for Engineers and Scientists*. Boca Raton: Chapman & Hall/CRC Press.
- Polyanin, A. D., Zaitsev, V. F. & Moussiaux, A. (2002). *Handbook of First Order Partial Differential Equations*. London: Taylor & Francis.
- Wazwaz, Abdul-Majid (2009). *Partial Differential Equations and Solitary Waves Theory*. Higher Education Press.

MODULE 3

- Unit 1 Second Order P.D.E. Classifications
Unit 2 Transformation of Independent Variables

UNIT 1 SECOND ORDER P.D.E. CLASSIFICATIONS**CONTENTS**

- 1.0 Introduction
- 2.0 Objectives
- 3.0 Main Content
 - 3.1 Second Order P.D.E Classifications
 - 3.2 The Tricomi's Equation
 - 3.3 Characteristics
 - 3.4 Case of Two Independent Variables
- 4.0 Conclusion
- 5.0 Summary
- 6.0 Tutor-Marked Assignment
- 7.0 References/Further Reading

1.0 INTRODUCTION

With specific reference to Second Order Partial Differential Equations, the various classifications are discussed with reference to the Tricomi's equation, characteristics, and case of two independent variables.

2.0 OBJECTIVES

At the end of this unit, you should be able to:

- classify Second Order Partial Differential Equations
- explain the importance of the Eigen-values of the matrix of coefficients
- state Tricomi's Equation
- work with Laplace, heat and Wave Equations
- describe the special case of two Independent Variables.

3.0 MAIN CONTENT

3.1 Second Order P.D.E. Classifications

A second order semi – linear equation

$$\sum_{j=1}^n A_{ij}(x) \frac{\partial^2 u}{\partial x_i \partial x_j} = g\left(x, u, \frac{\partial u}{\partial x_1}, \dots, \frac{\partial u}{\partial x_n}\right) \quad \dots\dots\dots (2.1.1)$$

Will be classified according to the properties of the Eigen-values of the matrix $(A_{ij}) = (A_{ji})$ of the coefficients of the highest order P.D.E. Derivations at any point x of a domain $\Omega \subset R^n$

- a. If all the Eigen-values are different from zero and all are of the same sign at x , the equation is said to be elliptic at the point x .

$$\begin{pmatrix} + + + & + + + \\ - - - & - - - \end{pmatrix}$$

- b. If all the Eigen-value are different from zero and all but one have the same sign at x . It means that the Partial Differential Equation is normal hyperbolic at x .

$$\begin{pmatrix} - + + + & + + + \\ + - - - & - - - \end{pmatrix}$$

- c. If all the Eigen-values are different from zero and there are at least two of each sign at x . The Partial Differential Equation is ultra hyperbaric at that pod.

$$\begin{pmatrix} - - + & + + + + \\ + + - - - - \end{pmatrix}$$

- d. If one Eigen-value is zero and the rest are of one sign at x . The Partial Differential Equation is parabolic at that point. If at least two Eigen-values are zero and the rest are of one sign at x . The equation is elliptic parabolic at that point.

$$\begin{pmatrix} 00 & + + + + + \\ 00 & - - - - - \end{pmatrix}$$

If an Eigen-value is zero and there is at least one positive and one negative at x , the equation is hyperbolic parabolic at

$x \begin{pmatrix} 0 & - & + & + & + & + \\ 0 & + & - & - & - & - \end{pmatrix} \begin{pmatrix} 0 & - & - & 1 & - & 1 \\ 0 & + & 1 & - & - & - \end{pmatrix}$. The Partial Differential Equation

(2.1.1) is said to be of one of the above types in a domain Ω in \mathbb{R}^n if it is so at every point x in Ω . Otherwise the equation is said to be of the mixed type in Ω . The above classification is applicable to quasi – linear second order equations.

$$\sum_{i,j=1}^n A(x, u, ux, \dots, ux_n) \frac{\partial^2 u}{\partial x_i \partial x_j} = g(x, u, ux, \dots, ux_n)$$

However, the sign of the solution $u(x)$ and the signs of the 1st order P.D.E derivation ux, r, \dots, ux_n may have to be known.

Examples:

a) A Laplace equation $\Delta u = 0$ is elliptic since

$$\Delta u = \frac{\partial^2 u}{\partial x^2} + \dots + \frac{\partial^2 u}{\partial x_n^2} = 0 \text{ and}$$

$$A_{ij} = \begin{pmatrix} 1 & 0 & 0 & \dots & 0 \\ 0 & 1 & 0 & \dots & 0 \\ \vdots & 1 & & & \vdots \\ 0 & \ddots & & & \vdots \end{pmatrix}$$

b) Heat Equation

$$\left(\Delta - \frac{\partial}{\partial t} \right) u = 0 \text{ is parabolic}$$

Since $\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial x_n^2} + \frac{\partial^2 u}{\partial t^2} - \frac{\partial u}{\partial t} = 0$ and

$$A_{ij} = \begin{pmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 & 0 & 1 & 1 \\ 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 & 0 \\ 0 & 0 & 0 & & & & & & \end{pmatrix}$$

$\lambda = 1, 1, 1, 1, 0$

c) Wave Equation

$$\boxed{u} = \left(\Delta - \frac{\partial^2}{\partial t^2} \right) u = 0$$

e.g. $\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} - \frac{d^2 y}{dz^2} = 0$

$$A_{ij} = \begin{pmatrix} 1 & 0 & - & - & - & 0 & 0 \\ 0 & 1 & - & - & - & 0 & 0 \\ \vdots & \vdots & \ddots & 1 & & & \\ 0 & \vdots & & - & 1 & & \end{pmatrix} \lambda = 1, 1, 1, - - - 1$$

It is normal hyperbolic

From $(x \ y \ z) \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix}$

$$a_{11}x^2 + 2a_{21}xy + 2a_{31}xz$$

$$+ 2a_{32}yz + a_{22}y^2 + a_{33}z^2$$

Exercise:

$$z \frac{\partial^2 u}{\partial x \partial y} + 2x \frac{\partial^2 u}{\partial y \partial z} = 0$$

$$\begin{pmatrix} \frac{\partial^2 u}{\partial x^2} & \frac{\partial^2 u}{\partial x \partial y} & \frac{\partial^2 u}{\partial x \partial z} \\ \frac{\partial^2 u}{\partial x \partial y} & \frac{\partial^2 u}{\partial y^2} & \frac{\partial^2 u}{\partial y \partial z} \\ \frac{\partial^2 u}{\partial x \partial z} & \frac{\partial^2 u}{\partial y^2 \partial z} & \frac{\partial^2 u}{\partial z^2} \end{pmatrix}$$

Is hyperbolic – parabolic in \mathbf{R}^3

$$A_{ij} = \begin{pmatrix} 0 & z & 0 \\ z & 0 & x \\ 0 & x & 0 \end{pmatrix}$$

Using $|A - \lambda I| = 0$

$$\begin{aligned}
 &= \begin{vmatrix} o-\lambda & z & o \\ z & o-\lambda & o \\ o & x & o-\lambda \end{vmatrix} \\
 &= \begin{vmatrix} -\lambda & z & o \\ z & -\lambda & o \\ o & x & -\lambda \end{vmatrix} \\
 &= -\lambda \begin{vmatrix} -\lambda & x \\ x & -\lambda \end{vmatrix} - z \begin{vmatrix} z & x \\ o & -\lambda \end{vmatrix} \\
 &= -\lambda (\lambda^2 - x^2) - z^2(-\lambda) \\
 &= -\lambda (\lambda^2 - x^2 - z^2) = 0 \\
 &\quad \lambda(x^2 + z^2 - \lambda^2) = 0 \\
 &\quad \lambda = 0 \text{ or } \pm\sqrt{x^2 + z^2}
 \end{aligned}$$

3.2 The Tricomi's Equation

Given by $y \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = 0$

$$A_{ij} = \begin{pmatrix} y & 0 \\ o & 1 \end{pmatrix}$$

This equation is of the mixed type elliptic for $y > 0$, parabolic for $y = 0$ and hyperbolic $y < 0$

3.3 Characteristics

Consider $\sum_{ij=1}^n A_{ij} \frac{\partial^2 u}{\partial x_i \partial x_j} = g(x, u, u_x, \dots, u_{xn}) \dots\dots\dots(2.5.1)$

Definition:

By the characteristic of (2.5.1) we mean the solution of the 1st order equation

$$\sum_{ij=1}^n A_{ij} \frac{\partial^2 u}{\partial x_i \partial x_j} = 0 \dots\dots\dots(2.5.2)$$

3.4 Case of Two Independent Variables

$$a(x, y) z_{xx} + 2b(x, y) z_{xy} + c(x, y) z_{yy} = \Phi(x, y, z, z_x, z_y) \dots\dots\dots 2.5.3$$

x and y are the independent variable and z the depend variable

$$A_{ij} = \begin{pmatrix} a & b \\ b & c \end{pmatrix}$$

Eigen-values are given by

$$\begin{aligned} |A - \lambda I| = 0 & \quad \begin{vmatrix} a - \lambda & b \\ b & c - \lambda \end{vmatrix} = 0 \\ & \Rightarrow \lambda^2 - (a + c)\lambda + ac - b^2 = 0 \\ & \Rightarrow \lambda_{1,2} = \frac{1}{2} \left\{ (a + c) \pm \sqrt{(a - c)^2 + 4b^2} \right\} \dots\dots\dots (2.5.4) \end{aligned}$$

Eigen-values are of different signs if

$$\begin{aligned} ac - b^2 < 0 \text{ and one is zero if} \\ ac - b^2 = 0 \end{aligned}$$

Therefore (2.5.3) is elliptic at x, y if $b^2 - ac < 0$

Hyperbolic at x, y if $b^2 - ac > 0$

Parabolic at x, y if $b^2 - ac = 0$ (2.5.5)

Equation 2.5.1 is one of these types in a domain Ω of xy plane if it is at any point of Ω .

No other type is possible since 2.5.4 can only admit two roots.

The characteristic equation is

$$a(x, y)(w_x)^2 + 2b(x, y)w_x w_y + c(x, y)(w_y)^2 = 0 \dots\dots\dots (2.5.6)$$

$$\begin{aligned} & \Rightarrow a p^2 + 2 b p q + c q^2 = 0 \\ & \Rightarrow p = q = 0 \text{ is a solution} \\ & \Rightarrow z(x, y) \text{ is a constant along a characterisation} \end{aligned}$$

$$\frac{\partial z}{\partial x} dx + \frac{\partial z}{\partial y} dy = 0 \quad (Z = w)$$

Equation 2.5.6 is homogenous wrt $w_x : w_y$. If we substitute for this with the proportional quantities dy and $-dx$, we then get

$$a(dy)^2 - 2b dx dy + c(dx)^2 = 0$$

$$\frac{dy}{dx} = \frac{b \pm \sqrt{b^2 - ac}}{a} \dots\dots\dots(2.5.7)$$

Which coincide with (2.5.3) a parabolic.

i Parabolic case $b^2 - ac = 0$

Let $E(x, y)$ be constant and the general solution of (2.5.7). Introduce a regular transformation.

$$\begin{aligned} E &= E(x, y) \\ y &= y(x, y) \end{aligned}$$

Where $y \in C^2(\Omega)$ is any function independent of E . The transformed characteristic equation

$$\bar{a}(\bar{z}_E)^2 + 2\bar{b}\bar{z}_E\bar{z}_y + \bar{c}(\bar{z}_y)^2 = 0 \dots\dots\dots(2.5.8)$$

has the solution $\bar{z} = E$

$$\text{So } \bar{a} = 0$$

Since a regular transformation does not alter the type of an equation

$$\bar{b}^2 = \bar{a}\bar{c}, \quad \bar{a} = 0$$

Divide the transformed P.D.E by \bar{C} to get the canonical form

$$\frac{\partial^2 z}{\partial^2 y} = \frac{\partial^2 u}{\partial^2 y} = \Phi(E, y, u, u_E, u_y) \dots\dots\dots(2.5.9)$$

- 1) Characteristics are invariant under regular transformation.
- 2) Type is not altered by a regular transformation.

4.0 CONCLUSION

Second order semi – linear Partial Differential Equations are classified according to the properties of their Eigen-values of the matrix of coefficients of the highest order.

5.0 SUMMARY

In this unit, we have been able to work with the classification of second order Partial Differential Equation with a special focus on the Tricomi’s equation, characteristics and the case of two independent variables.

6.0 TUTOR-MARKED ASSIGNMENT

1. Reduce to canonical form and find the general solution from

$$y^2 u_{xx} - 2y u_{xy} + u_{yy} = u_x + 6y$$
2. Find the characteristic of

$$a(x, y)u_{xx} + b(x, y)u_{xy} + c(x, y)u_{yy} = d(x, y, u, u_x, u_y)$$

7.0 REFERENCES/FURTHER READING

- Adomian, G. (1994). *Solving Frontier Problems of Physics: The Decomposition Method*. Kluwer Academic Publishers.
- Courant, R. & Hilbert, D. (1962). *Methods of Mathematical Physics II*. New York: Wiley-Interscience.
- Evans, L. C. (1998). "Partial Differential Equations". Providence. *American Mathematical Society*.
- Jost, J. (2002). *Partial Differential Equations*. New York: Springer-Verlag.
- Petrovskii, I. G. (1967). *Partial Differential Equations*. Philadelphia: W. B. Saunders Co.
- Pinchover, Y. & Rubinstein, J. (2005). *An Introduction to Partial Differential Equations*. New York: Cambridge University Press.
- Polyanin, A. D. & Zaitsev, V. F. (2004). *Handbook of Non-linear Partial Differential Equations.*, Boca Raton: Chapman & Hall/CRC Press.
- Polyanin, A. D. (2002). *Handbook of Linear Partial Differential Equations for Engineers and Scientists*. Boca Raton: Chapman & Hall/CRC Press.
- Polyanin, A. D., Zaitsev, V. F. & Moussiaux, A. (2002). *Handbook of First Order Partial Differential Equations*. London: Taylor & Francis.
- Wazwaz, Abdul-Majid (2009). *Partial Differential Equations and Solitary Waves Theory*. Higher Education Press.

UNIT 2 TRANSFORMATION OF INDEPENDENT VARIABLES

CONTENTS

- 1.0 Introduction
- 2.0 Objectives
- 3.0 Main Content
 - 3.1 Transformation of Independent Variables
 - 3.1.1 Regular Case
 - 3.1.2 Hyperbolic Case
 - 3.1.3 Elliptic Case
- 4.0 Conclusion
- 5.0 Summary
- 6.0 Tutor-Marked Assignment
- 7.0 References/Further Reading

1.0 INTRODUCTION

Sometimes it can be expedient to transform the independent variables in solving Partial Differential Equations with Regular case, Hyperbolic case and Elliptic case. Proof of theorem is presented that regular transformation of independent variable does not alter the type of Partial Differential Equations.

2.0 OBJECTIVES

At the end of this unit, you should be able to:

- transform independent variables
- apply the theorems to the regular case
- solve equations of the hyperbolic types by transformations
- explain why Elliptic equations have no real characteristics.

3.0 MAIN CONTENT

3.1 Transformation of Independent Variables

Let $E = \Sigma(x, y)$ $\gamma = \gamma(x, y)$ be a regular transformation $\Leftrightarrow 1-1$

$$\begin{aligned} \overline{JJ} &= \frac{\partial(E, \gamma)}{\partial(x, y)} \\ &= \begin{vmatrix} E_x & E_y \\ \gamma_x & \gamma_y \end{vmatrix} \neq 0 \end{aligned}$$

$$\begin{aligned} \Leftrightarrow \quad & x = x(E, \gamma) \\ & y = y(E, \gamma) \\ & U_x \frac{\partial u}{\partial x} = \frac{\partial u}{\partial E} \frac{\partial E}{\partial x} + \frac{\partial u}{\partial \gamma} \frac{\partial \gamma}{\partial x} \\ & = U_E E_x + U_\gamma \gamma_x \end{aligned}$$

Similarly

$$\begin{aligned} U_y &= U_E E_y + U_\gamma \gamma_y \\ U_{xx} &= U_{EE} E_x^2 + 2U_{E\gamma} \gamma_x E_x + U_{\gamma\gamma} \gamma_x^2 \\ &\quad + U_E E_{xx} + U_\gamma \gamma_{xx} \\ U_{yy} &= U_{EE} E_y^2 + 2U_{E\gamma} \gamma_y E_y + U_{\gamma\gamma} \gamma_y^2 \\ &\quad + U_E E_{yy} + U_\gamma \gamma_{yy} \\ U_{xy} &= U_{EE} E_x E_y + U_{E\gamma} (\gamma_x E_y + E_x \gamma_y) + U_{\gamma\gamma} \gamma_x \gamma_y \\ &\quad + U_E E_{xy} + U_\gamma \gamma_{yx} \end{aligned}$$

Substitute U_{xx}, U_{xy}, U_{yy} in

$$a(x, y)U_{xx} + 2b(x, y)U_{xy} + C(x, y)U_{yy} = \Phi(x, y, u, ux, uy)$$

We get

$$\begin{aligned} & \tilde{a}(E, \gamma)U_{EE} + \tilde{b}(E, \gamma)U_{E\gamma} + \tilde{c}(E, \gamma)U_{\gamma\gamma} \\ & = \Phi(E, \gamma, U, U_E, U_\gamma) \dots\dots\dots(2.5.9) \end{aligned}$$

Where

$$\begin{aligned} \tilde{a} &= a E^2 + 2bE_x E_y + CE_y^2 \\ \tilde{b} &= a E_x \gamma_x + b (E_x \gamma_y + E_y \gamma_x) + CE_y \gamma_y \\ \tilde{c} &= a \gamma_x^2 + 2b \gamma_x \gamma_y + C \gamma_y^2 \\ b^2 - a &= \Delta (\Delta \text{ is criminant}) (E_x \gamma_y - \gamma_x E_y)^2 \\ \tilde{b}^2 - \tilde{a} \tilde{c} &= (b^2 - ac)^2 \\ &= (b^2 - ac) \overline{JJ}^2 \end{aligned}$$

The steps that led to the result is a proof of the theorem that regular transformation of independent variable does not alter the type of P.D.E.

3.1.1 Regular Case

Theorem

Characteristics are invariant under regular transformation.

Proof

Equation of characteristics

$$a \left(\frac{\partial w}{\partial x} \right)^2 + 2b \frac{\partial w}{\partial x} \frac{\partial w}{\partial y} + c \left(\frac{\partial w}{\partial y} \right)^2 = 0 \dots\dots\dots(2.5.10)$$

$$wx = w_E E_x + w_\gamma \gamma_x$$

$$wy = w_E E_y + w_\gamma \gamma_y$$

Substituting into (2.5.10) It will be shown that it is the same as

$$\hat{a} w_w^2 + 2 \hat{b} w_E w_\gamma + \hat{c} w \gamma^2 = 0$$

Where

$$\hat{a} = aE_x^2 + 2bE_xE_y + cE_y^2$$

$$\hat{b} = aE_x\gamma_x + b(E_x\gamma_y + \gamma_xE_y) + cE_y\gamma_y$$

$$\hat{c} = a\gamma_x^2 + 2b\gamma_x\gamma_y + c\gamma_y^2$$

3.1.2 Hyperbolic Case ($b^2 - ac > 0$)

Let $E(x,y) = \text{constant}$, $\gamma(x,y) = \text{constant}$ from the general solution of (2.5.7). Then (2.5.10) has two independent solutions.

$$w = E, w = \gamma$$

$$\Rightarrow \hat{a} = \hat{c} = 0$$

Divide the transformed equations by $2\hat{b}$ to obtain

$$\frac{\partial^2 u}{\partial E \partial \gamma} = \Phi(E, \gamma, U, U_E, U_\gamma) \dots\dots\dots (2.5.11)$$

Let
$$\begin{aligned} E_i &= E + \gamma & \Leftrightarrow & E = \frac{1}{2}(E_i + \gamma_i) \\ \gamma_i &= E - \gamma & & \gamma = \frac{1}{2}(E_i - \gamma_i) \end{aligned} \dots\dots\dots (2.5.12)$$

be a linear transformation

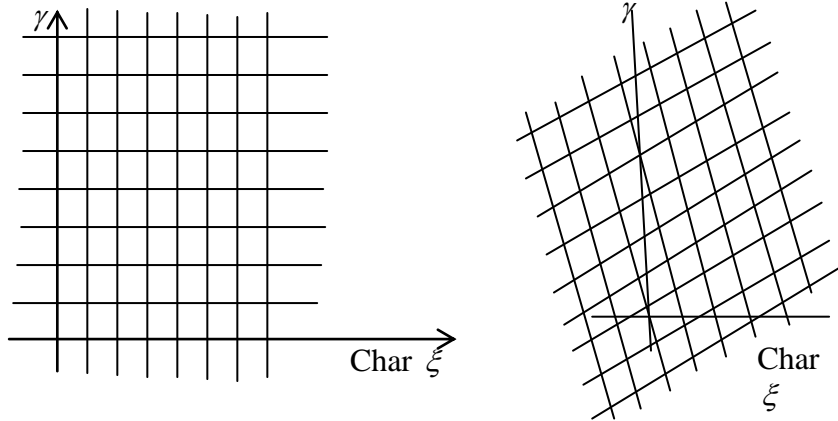
$$\frac{\partial}{\partial E} = \left(\frac{\partial}{\partial E_i} + \frac{\partial}{\partial \gamma_i} \right), \frac{\partial}{\partial \gamma} = \frac{\partial}{\partial E_i} - \frac{\partial}{\partial \gamma_i}$$

Substituting into (2.5.11) yields

$$= \frac{\partial}{\partial E} \frac{\partial}{\partial \gamma} (u)$$

$$\begin{aligned}
 &= \left(\frac{\partial}{\partial E_i} + \frac{\partial}{\partial \gamma} \right) \left(\frac{\partial}{\partial E_i} - \frac{\partial}{\partial \gamma} \right) u \\
 &= \frac{\partial^2 u}{\partial E^2} - \frac{\partial^2 u}{\partial \gamma^2} = \Phi_2(E_i, \gamma_i, U, U_E, U_\gamma) \dots\dots\dots(2.5.13)
 \end{aligned}$$

In the $E \gamma$ - plane, the characteristic are lines ↗ to the coordinate areas while in $E_i \gamma_i$ - plane they are lines of slopes ± 1



3.1.3 Elliptic Case ($b^2 - ac < 0$)

Theorem

An Elliptic equation has no real characteristics

Proof

The characteristics are $\left(\frac{dy}{dx} \right)_{1,2} = \frac{b \pm \sqrt{b^2 - ac}}{a}$

But $b^2 - ac < 0$ this \Rightarrow that \nexists no real curve in the real x - y plane. We assume that a, b, c admits complex values. Equation (2.5.7) becomes P.D.Es in a complex values domain suppose $w(x, y) \neq \text{constant}$ is a general solution of the 1st order equation, then $w(x, y) \neq$ satisfying (2.5.10)

Suppose $w(x, y) = E(x, y) + \gamma(x, y)$

Where x, y, E, γ are real

$$\overline{JJ} = \frac{\partial(E, \gamma)}{\partial(x, y)} \neq 0$$

For if $\overline{JJ} = 0$ at (x, y)

$$\frac{\partial E}{\partial x} = \lambda \frac{\partial E}{\partial y}$$

$$\frac{\partial E}{\partial x} = \lambda \frac{\partial \gamma}{\partial y}$$

$$\frac{\partial w}{\partial x} = \lambda \frac{\partial w}{\partial y} \text{ for some } \lambda \in R$$

Substitute in 2.5.10

$$a(wx)^2 + 2bw_\lambda w_y + c(wy)^2 = 0$$

We have

$$a\lambda^2 + 2b\lambda + c = 0$$

Since $wx = \lambda wy$

$$a(\lambda wy)^2 + 2b\lambda wy wy + c(wy)^2 = 0$$

$$a\lambda^2 (wy)^2 + 2b\lambda + c \quad wy = 1$$

$$a\lambda^2 + 2b\lambda + c$$

Which has real root this is impossible since $b^2 - ac < 0$, therefore $\overline{JJ} \neq 0$

Take $E = E(x, y)$ and $\gamma = \gamma(x, y)$ as the new independent variables equation 2.5.10 must be satisfied by $w = E + 1\gamma$

$$\Rightarrow \quad \widehat{a} (wE)^2 + 2\widehat{b} wE w\gamma + \widehat{c} (w\gamma)^2 = 0$$

$$\widehat{a} + 2\widehat{b}i + \widehat{c}i^2 = 0$$

$$\widehat{a} - \widehat{c} + 2\widehat{b}i = 0$$

$$\Rightarrow \quad \widehat{a} - \widehat{c} = 0 \quad \Rightarrow \widehat{a} = \widehat{c}$$

$$2\widehat{b} = 0 \quad \Rightarrow \widehat{b} = 0$$

Dividing the transformation equation by \widehat{a} , we arrived at the canonical form

$$\frac{\partial^2 u}{\partial E^2} + \frac{\partial^2 u}{\partial \gamma^2} = \Phi(E, \gamma, U, U_E, U_\gamma) \dots\dots\dots(2.5.14)$$

Examples:

Solve the Partial Differential Equation by the method of characteristics

$$yu_{xx} + (x+y)u_{xy} + xu_{yy} = 0$$

Sketch the characteristics curves

$$\text{Have } a = y, \quad b = \frac{1}{2}(x+y), \quad c = \lambda$$

$$\text{So } b^2 - ac = \frac{1}{4}(x-y)^2$$

Which implies that the equation is hyperbolic for $x \neq y$, parabolic for $x = y$ the characteristics equations

$$\frac{dy}{dx} = \frac{\frac{1}{2}(x+y) + \frac{1}{2}(x-y)}{y} = \frac{x}{y} \text{ both are separable equation}$$

$$\frac{dy}{dx} = \frac{\frac{1}{2}(x+y) - \frac{1}{2}(x-y)}{y} = 1$$

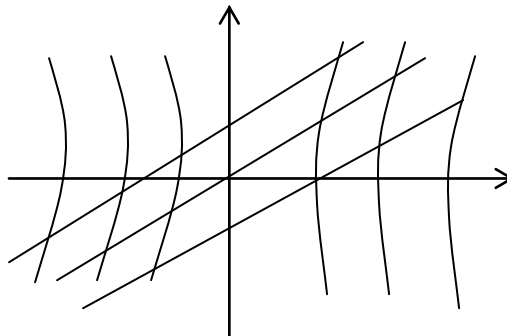
then solving it \Rightarrow

$$\begin{aligned} y^2 - x^2 &= \alpha : r_1 \quad y \, dy = x \, dx \\ y - x &= \beta : r_2 \quad \frac{y^2}{2} - \frac{x^2}{2} = 8 \\ & \quad \quad \quad y^2 - x^2 = \beta = 28 \end{aligned}$$

where r_1, r_2 are the characteristics curves

r_1 is defined as rectangular hyperboles

r_2 is defined as straight line with slope



Now write
$$\begin{aligned} y^2 - x^2 &= E(x, y) \\ y - x &= \gamma(x, y) \end{aligned}$$

$U(x, y)$ can be transformed into

$$U_x = \frac{\partial u}{\partial x} = \frac{\partial u}{\partial E} \frac{\partial E}{\partial x} + \frac{\partial u}{\partial \gamma} \frac{\partial \gamma}{\partial x}$$

$$U_x = -2xU_E - U_\gamma$$

$$U_y = \frac{\partial u}{\partial E} \frac{\partial E}{\partial y} + \frac{\partial u}{\partial \gamma} \frac{\partial \gamma}{\partial y} \quad U_y = 2yU_E + U_\gamma$$

$$U_{xx} = 4x^2U_{E\gamma} + 4xU_{E\gamma} + U_{\gamma\gamma} - 2U_E$$

$$U_{xy} = -4xyU_{EE} - 2U_{E\gamma}(y+x) - U_{\gamma\gamma}$$

$$U_{yy} = 4y^2U_{EE} + 4yU_{E\gamma} + U_{\gamma\gamma} + 2U_E$$

The Partial Differential Equation (x) becomes

$$-2U_E \gamma (y^2 + x^2 - 2xy) - 2U_E (y - x) = 0$$

So that we now have

$$-2\gamma^2 U_E \gamma - 2\gamma U_E = 0$$

We now have

$$2\gamma (\gamma U_{E\gamma} + U_E) = 0$$

$$\Rightarrow \gamma U_{E\gamma} + U_E = 0$$

$$\gamma \frac{\partial}{\partial \gamma} \left(\frac{\partial u}{\partial E} \right) + \frac{\partial u}{\partial E} = 0$$

Let $w = U_E$

$$\gamma W_\gamma + w = 0$$

$$\frac{\partial}{\partial \gamma} \left(\gamma \frac{\partial u}{\partial E} \right) = 0$$

$$\gamma \frac{\partial u}{\partial E} = F(E)$$

$$\frac{\partial u}{\partial E} = \frac{1}{\gamma} F(E)$$

$$U(E, \gamma) = \frac{1}{\gamma} \int F(E) dE + G(\gamma)$$

Where

$$F(E) = \int F(E) dE$$

$$\Phi(x, y) U(x, y) = \frac{1}{y-x} F(y^2 - x^2) + G(y-x)$$

Where F and G are arbitrary differentiable functions

Exercise:

Solve the following 2nd order P.D.E by the method of characteristics

$$U_{xx} + 2U_{xy} + U_{yy} + U_x + U_y = 0$$

Sketch the characteristics

$$a = 1 \quad b = 1 \quad c = 1$$

$$b^2 - ac = 0$$

Further Exercise

Classify and solve the following P.D.Es by the method of characteristics and sketch the characteristics

i) $y^2 U_{xx} - 2y U_{xy} + U_{yy} - U_x - 6y = 0$

ii) $U_{xx} + x^2 U_{yy} = 0$

iii) $u_{xx} + x U_{yy} = 0$
 $\Rightarrow F\left(y + \frac{1}{4}i\right) + x g\left(y + \frac{1}{4}i\right)$
 $F\left(2y + x^2i\right) + G\left(2y - x^2\right)$

4.0 CONCLUSION

Regular transformation of independent variables does not alter the type of a Partial Differential Equation.

5.0 SUMMARY

The potential of transformations to ease the arrival at solution of Partial Differential Equation never be understated and this was adequately demonstrated in the transformation of independent variables with three specific scenarios of the regular, hyperbolic and the elliptic cases visited.

6.0 TUTOR-MARKED ASSIGNMENT

1. Let a, b be real numbers. The Partial Differential Equation

$$u_y + au_{xx} + bu_{yy} = 0$$

is to be solved in the box $\Omega = [0, 1] \times [0, 2]$.

2. Find data, given on an appropriate part of $\partial\Omega$, that will make this a well-posed problem and cover all cases according to the possible values of a and b .

Justify your answer.

7.0 REFERENCES/FURTHER READING

Adomian, G. (1994). *Solving Frontier Problems of Physics: The Decomposition Method*. Kluwer Academic Publishers.

Courant, R. & Hilbert, D. (1962). *Methods of Mathematical Physics II*. New York: Wiley-Interscience.

- Evans, L. C. (1998). "Partial Differential Equations". Providence: *American Mathematical Society*.
- Jost, J. (2002). *Partial Differential Equations*. New York: Springer-Verlag.
- Petrovskii, I. G. (1967). *Partial Differential Equations*. Philadelphia: W. B. Saunders Co.
- Pinchover, Y. & Rubinstein, J. (2005). *An Introduction to Partial Differential Equations*. New York: Cambridge University Press.
- Polyanin, A. D. & Zaitsev, V. F. (2004). *Handbook of Non-linear Partial Differential Equations*. Boca Raton: Chapman & Hall/CRC Press.
- Polyanin, A. D. (2002). *Handbook of Linear Partial Differential Equations for Engineers and Scientists*. Boca Raton: Chapman & Hall/CRC Press.
- Polyanin, A. D., Zaitsev, V. F. & Moussiaux, A. (2002). *Handbook of First Order Partial Differential Equations*. London: Taylor & Francis.
- Wazwaz, Abdul-Majid (2009). *Partial Differential Equations and Solitary Waves Theory*. Higher Education Press.

MODULE 4

Unit 1 Cauchy Problem, Characteristics Problem and Fundamental Existence Theorem

UNIT 1 CAUCHY PROBLEM, CHARACTERISTICS PROBLEM AND FUNDAMENTAL EXISTENCE THEOREM**CONTENTS**

- 1.0 Introduction
- 2.0 Objectives
- 3.0 Main Content
 - 3.1 Cauchy Problem and Characteristics Problem
 - 3.2 Fundamental Existence Theorem
 - 3.2.1 Cauchy Problem
 - 3.2.2 Cauchy Kovalevsky Theorem
- 4.0 Conclusion
- 5.0 Summary
- 6.0 Tutor-Marked Assignment
- 7.0 References/Further Reading

1.0 INTRODUCTION

This unit zooms in on Cauchy problem and the Cauchy Kovalevsky theorem and places their significance in the solving of higher order Partial Differential Equations into context.

2.0 OBJECTIVES

At the end of this unit, you should be able to:

- solve Cauchy Problem and Characteristics Problem
- explain the strip condition
- treat the fundamental existence theorem
- explain the method of solving Cauchy Problem
- solve problems using the Cauchy Kovalevsky Theorem.

3.0 MAIN CONTENT

3.1 Cauchy Problem and Characteristics Problem

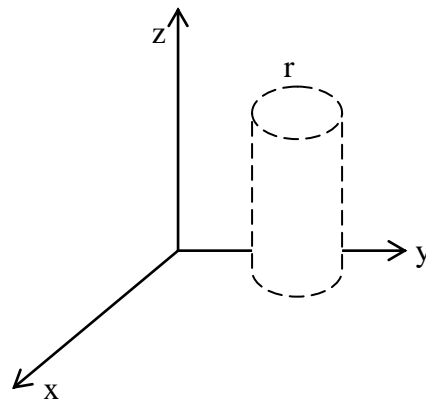
Find a solution

$U = U(x, y)$ of the equation
 $aU_{xx} + 2bU_{xy} + cU_{yy} = \Phi(x, y, u, p, q)$ in some neighbourhood of

a space curve, set $u = z$
 $r = \{(x, y, z) : x = f_1(t), y = f_2(t), z = h(t)\}$
 $0 \leq t \leq 1$

Such that

$$\begin{aligned} \frac{z}{n} &= h(x, y), \\ \frac{\partial z}{\partial n} &= H(x, y) \end{aligned}$$



If instead of prescribing

$$\frac{\partial z}{\partial n} \text{ on } r, \frac{\partial z}{\partial x} = p, \frac{\partial z}{\partial y} = q \text{ are prescribed}$$

We find that f_1, f_2, h, p, q must satisfy

$$\begin{aligned} \frac{dz}{dt} &= h'(t) = z_x x_t + z_y y_t \dots\dots\dots(2.7.2) \\ &= pf_1' + q f_2' \end{aligned}$$

This is known as the strip conditions. Cauchy problem therefore becomes that of finding a solution of (2.7.1) containing the integral strip of (f_1, f_2, h, p, q) at any point of the integral strip.

$$\frac{dp}{dt} = z_{xx} \frac{dx}{dt} + z_{xy} \frac{dy}{dt} = r\bar{f}_1 + sf_2^1 \dots\dots\dots(2.7.3)$$

$$\frac{dp}{dt} = z_{xy} \frac{dx}{dt} + z_{yy} \frac{dy}{dt} = \bar{f}_1 + rf_2^1 \dots\dots\dots(2.7.3b)$$

Solving (2.7.1) and (2.7.3) above, we have

$$\frac{r}{\Delta} = \frac{s}{\Delta_2} \frac{r}{\Delta_3} = \frac{1}{\Delta}$$

Where

$$\Delta = \begin{vmatrix} a & 2b & c \\ f_2^1 & f_2^1 & o \\ o & f_1^1 & f_2^1 \end{vmatrix}$$

Now

$$\Delta_1 = \begin{vmatrix} \Phi & 2b & c \\ p^1 & f_2^1 & o \\ q^1 & f_1^1 & f_2^1 \end{vmatrix}$$

$$\Delta_2 = \begin{vmatrix} a & \Phi & c \\ f_1^1 & p_2^1 & o \\ o & q^1 & f_2^1 \end{vmatrix}$$

$$\Delta_3 = \begin{vmatrix} a & 2b & \Phi \\ f_1^1 & f_2^1 & p^1 \\ o & f_1^1 & q^1 \end{vmatrix}$$

If $\Delta \neq 0$, we can uniquely determine r, s, r on c differentiating (2.7.1) with respect to t and using the relations

$$\frac{dr}{dt} = \frac{\partial^3 z}{\partial x^3} \frac{dx}{dt} + \frac{\partial^3 z}{\partial y \partial x^2} \frac{dy}{dt} = Z_{xxx} f_1^1 + Z_{xxy} f_2^1$$

$$\frac{ds}{dt} = \frac{\partial^3 z}{\partial x^2} \frac{dx}{dt} + \frac{\partial^3 z}{\partial y \partial x^2} \frac{dy}{dt} = Z_{xxy} f_1^1 + Z_{xyy} f_2^1$$

$$\frac{dr}{dt} = \frac{\partial^3 z}{\partial x \partial y^2} \frac{dx}{dt} + \frac{\partial^3 z}{\partial y \partial x^2} \frac{dy}{dt} = Z_{xyy} f_1^1 + Z_{yyy} f_2^1$$

3rd order derivations of c can be calculated on Z, similarly for fourth and higher order partial derivatives. The value of Z in some neighbourhood of r can be obtained by Taylor's theorem

The Cauchy problem passes a unique solution $\Delta \neq 0$

Suppose that $\Delta \neq 0$, then

$$\begin{aligned} a(f_2^1)^2 - 2bf_1^1 f_2^1 + c(f_1^1)^2 &= 0 \\ \Rightarrow a \left(\frac{dy}{dt}\right)^2 - 2b \frac{dx}{dt} \frac{dy}{dt} + c \left(\frac{dx}{dt}\right)^2 &= 0 \\ \Rightarrow a(dy)^2 + 2b dx dy + c(dx)^2 &= 0 \end{aligned}$$

Which is the equation for characteristics of (2.7.1) however, if $\Delta = 0$ and $\Delta_i (i = 1, 2, 3)$, a solution will exist but not unique.

3.2 Fundamental Existence Theorem

3.2.1 Cauchy Problem

Given a Partial Differential Equation, find a solution which satisfied given boundary or initial conditions if the conditions are enough to ensure existence, uniqueness and continuous dependence of the solution on the given data a Cauchy data. We say that the problem is well posed.

3.2.2 Cauchy Kovalevsky Theorem

Solutions of initial value problems may be obtained in Taylor’s series. We simply compute the coefficients of the Taylor’s series of the solution using initial data and the Partial Differential Equation. The method is possible if the solution is analytic. Cauchy Kovalevsky theorem gives the condition under which the initial – value problem has solution which is an analytic function.

Case 1 (1st Order Equation \mathbb{R}^2)

$$\begin{cases} F(t), x, u, u_t, u(x) = 0 \\ u(o, x) \qquad \qquad \qquad \phi(x) \end{cases}$$

Assume

$$\begin{cases} ut = f(t, x, u, u_x) & \dots\dots\dots (3.1.1) \\ u(o, x = \Phi(x) & \dots\dots\dots (3.1.2) \end{cases}$$

Let $\Phi(x)$ be analytic in the neighbourhood of the origin $x = 0$, f is analytic in the neighbourhood of the point $(0, 0, \Phi(0), \Phi^1(0)) \in \mathbb{R}^4$

Then the Cauchy – problem (3.1.1) to (3.1.2) has a solution $u(t, x)$

Which is defined and analytic in a neighbourhood of the origin $(0, 0) \in \mathbb{R}^2$ and this solution is unique in the class of analytic functions.

Proof

The proof depends essentially on a specific technique. Assuming Φ is analytic in a neighbourhood of $x = 0$ this enables us to obtain

$$\frac{\partial^n u}{\partial x^n}(0,0) = f(\Phi^n(0)) \quad n = 1, 2, 3, \dots$$

From (3.1.1) $u_t(0,0) = f(0, 0, \Phi(0), \Phi'(0))$

Differentiating (3.1.1) wrt x

$$u_{tx}(t,x) = \frac{\partial f}{\partial t} \frac{\partial t}{\partial x} + \frac{\partial f}{\partial x} \frac{\partial x}{\partial x} + \frac{\partial f}{\partial u} \frac{\partial u}{\partial x} + \frac{\partial f}{\partial ux} \frac{\partial ux}{\partial x}$$

$$U_{tx}(t,x) = f_x + f_u u_x + f_{ux} U_{xx}$$

Since f is known and U_x, U_{xx} have being determined at the origin. We can find $U_{xt}(0,0)$ to obtain U_{xxt} we differential (3.1.1) twice with respect to x and substitute $t = x = 0$ and also previously determined values of U, U_x, U_{xx}, U_{xxx} at $(0,0)$

Continuing in this manner, we can determine the values of all partial derivatives

$$\frac{\partial^{n+1} u}{\partial x^n \partial t}; \quad n = 0, 1, 2, \dots \text{at } (0,0)$$

Differentiating (3.1.1) wrt t

$$U_{tt} = f_t + f_u U_t + f_{ux} U_{xt}$$

Substituting $t = x = 0$ and previously obtained values of u, u_x, u_t at $(0,0)$. Continuing in this way, we obtain the values of all partial derivatives of u at $(0,0)$.

$$U(t,x) = \sum_{\alpha=0}^{\infty} \sum_{\beta=0}^{\infty} \frac{D_t^\alpha D_x^\beta u(0,0) t^\alpha x^\beta}{\alpha! \beta!} \dots\dots\dots(3.1.3)$$

Cauchy Kovalovsky's theorem assert that this series converges for all (t,x) in some neighbourhood of the origin $(0,0)$ and defines the solution of (3.1.1) in this neighbourhood. Uniqueness follows from the fact that any two analytic functions having the same Taylor's series coefficients are identical.

Examples:

$$U_t = Uux$$

$$U(0, x) = 1 + x^2$$

Taylor's series expansion

$$\begin{aligned} U(t, x) &= U(0,0) + U_t(0,0)t + U_x(0,0)x + \\ &\frac{1}{2!} \{ U_{tt}(0,0)t^2 + 2U_{tx}(0,0)tx + U_{xx}(0,0)x^2 \} \\ &+ \frac{1}{3} \{ U_{ott}(0,0)t^3 + \dots \end{aligned}$$

$\Phi(x) = 1 + x^2$ is analytic in the neighbourhood of $x = 0$ (analytic in x)

$f(t, x, u, ux) = uux$ is analytic in the neighbourhood $(0,0,1,0) \in \mathfrak{R}^4$

$$u(0, x) = \Phi(x) = 1 + x^2$$

$$u(0,0) = \Phi(0) = 1$$

$$u_x(0,0) = 2x \text{ at } x = 0 = 0$$

$uux = \int (t, x, u, ux)$ is analytic in the neighbourhood of point $(0, 0, 1, 0) \in \mathfrak{R}^4$

$$u(0, x) = 1 + x^2 \quad u(0,0) = 1$$

$$ux(0, x) = 2x \quad ux(0,0) = 0$$

$$u_{xx}(0, x) = 2 \quad u_{xx}(0,0) = 2$$

$$D_x^n u(0, x) = 0, \quad n \geq 3$$

$$D_x^n u(0,0) = 0, \quad n \geq 3$$

$$u_t = uux \quad u_t(0,0) = u(0,0)ux(0,0) = 1 \times 0 = 0$$

$$u_{tt} = u_x^2 + u_{uux} \quad u_{tt}(0,0) = 0 + 1 \times 2 = 2$$

$$u_{ttt} = u_{tt}ux + u_{uxt}, \quad u_{ttt}(0,0) = 2$$

$$u_{ttx} = 3ux_{u_{xx}} + u_{u_{xxx}}; \quad u_{ttx}(0,0) = 0$$

$$u_{ttt} = u_{tt}ux + 2ux_{u_{tx}} - u_{uttx}; \quad u_{ttt}(0,0) = 0$$

$$u_{ttt}(0,0) = 0$$

Neglecting terms of order ≥ 4

$$\begin{aligned} u(x, t) &= \sum_{\alpha=0} \sum_{\beta=0} \frac{D_t^\alpha D_x^\beta u(0,0) t^\alpha x^\beta}{\alpha! \beta!} \\ &= 1 + 0 + 0 + t^2 + 2tx + x^2 \\ &= 1 + t^2 + 2tx + x^2 + \dots \end{aligned}$$

Exercise:

Let $u(x, y)$ satisfy $ux^2 + uy^2 = 1$ and let $u(0, y) = \Phi(y) + y$. Determine the Taylor's series expansion of $u(x, y)$ and sum the series to show that

$$u(x, y) = \Phi_1(y)x + \Phi(y)$$

2nd Order Equation in \mathbb{R}^2

We want to consider Partial Differential Equation of the form

$$F(t, x, u, ut, ux, uxx, utt, utx) = 0$$

Assume $utt = F(t, x, u, ut, ux, utx, uxx)$

The Cauchy problem in this case will be

$$\begin{cases} utt = F(t, x, u, ut, ux, utx, uxx) \\ u(0, x) = \Phi(x) \\ ut(0, x) = \Psi(x) \end{cases}$$

($t = 0$ is not characteristic)

Theorem:

Let $\Phi(x), \Psi(x)$ be analytic in a nbd of the origin $x = 0$ in \mathbb{R} and suppose f is analytic in a nbd of the point $(0, 0, \Phi(0), \Phi'(0), \Psi(0), \Psi'(0)) \in \mathbb{R}^n$. The Cauchy problem (3.14) – (3.16) has a solution $u(t, x)$ which is defined and analytic in a nbd of the origin $t = 0, x = 0$ of \mathbb{R}^2 and this solution is unique in the class of analytic functions.

Outline of technique:

From (3.15) and (3.16) we obtain

$$\begin{aligned} \frac{\partial^n u}{\partial x^n}(0, 0) &= \Phi^n(0) \\ \frac{\partial^{n+1} u}{\partial t \partial x^n}(0, 0) &= \Psi^n(0) \end{aligned}$$

Differentiating (3.14) successively and using the calculated values, we find all the coefficients in the Taylor's series solution as before.

Examples:

- 1) Let $u(x, y)$ satisfy $u_{xx} + u_{yy} = 0$ and let $u(0, y) = \sin y$

$$u(0, y) = \sin y$$

Determine the Taylor's series expansion for the solution $u(x, y)$ of Partial Differential Equation and sum the series to show that

$$u(x, y) = \sin y \cosh x + xy$$

- 2) Find the former series solution for the Partial Differential Equation

$$y^2 u_{xx} = x^2 u_{yy} + 2(x^2 - y^2)u$$

$$u(0, y) = e^{-y^2}$$

$$u_x(0, y) = 0$$

$$u_{xx} - u_{yy} = f(x, y, u, u_x, u_y, u_{xy}, u_{yy})$$

$$u(0, y) = \sin y$$

$$u_x(0, y) = y$$

$$u(x, y) = u(0,0) + x u_x(0,0) + y u_y(0,0) +$$

$$\frac{1}{2} \xi u_{xx} 10 dx^2 + \dots\dots\dots$$

$$u(0,0) = \sin 0$$

$$u_x(0,0) = 0$$

$$u_y(0,0) = 1$$

$$u_{yy}(0,0) = \cos 0$$

$$u_{yy} = -\sin y$$

- 3) $y^2 u_{xx} = x^2 u_{yy} + 2(x^2 - y^2)u$

$$u(0,0) = 1$$

$$u_x(0,0) = 0$$

$$u_y(0, y) = 2y e^{-y^2} - 0$$

$$u_{xx} = 0$$

$$u_{xy} = 0$$

$$u_{yy} = -2y(-2y e^{-y^2}) - 2e^{-y^2}$$

$$= -2$$

4.0 CONCLUSION

Cauchy problem can be summed up as the problem of finding a solution containing the integral strip of functions at any point of the integral strip while Cauchy Kovalevsky theorem simply states the condition under which an initial – value problem has an analytic function solution.

5.0 SUMMARY

We have seen in this unit that Cauchy problem, Characteristics problem and Cauchy Kovalevsky theorem are useful in addressing certain types of partial differential equations

6.0 TUTOR-MARKED ASSIGNMENT

1. Solve the Cauchy problem

$$\begin{aligned}u_t - xuu_x &= 0 & -\infty < x < \infty, t \geq 0 \\u(x, 0) &= f(x) & -\infty < x < \infty.\end{aligned}$$

and find a class of initial data such that this problem has a global solution for all t . and then, compute the critical time for the existence of a smooth solution for initial data, f , which is not in the above class.

2. Find an implicit formula for the solution u of the initial-value problem

$$\begin{aligned}u_t &= (2x - 1)tu_x + \sin(\pi x) - t, \\u(x, t = 0) &= 0.\end{aligned}$$

Evaluate u explicitly at the point $(x = 0.5, t = 2)$.

7.0 REFERENCES/FURTHER READING

Adomian, G. (1994). *Solving Frontier Problems of Physics: The Decomposition Method*. Kluwer Academic Publishers.

Courant, R. & Hilbert, D. (1962). *Methods of Mathematical Physics II*. New York: Wiley-Interscience.

Evans, L. C. (1998). "Partial Differential Equations". Providence: American Mathematical Society.

Jost, J. (2002). *Partial Differential Equations*. New York: Springer-Verlag.

Petrovskii, I. G. (1967). *Partial Differential Equations*. Philadelphia: W. B. Saunders Co.

Pinchover, Y. & Rubinstein, J. (2005). *An Introduction to Partial Differential Equations*. New York: Cambridge University Press.

Polyanin, A. D. & Zaitsev, V. F. (2004). *Handbook of Non-linear Partial Differential Equations*. Boca Raton: Chapman & Hall/CRC Press.

Polyanin, A. D. (2002). *Handbook of Linear Partial Differential Equations for Engineers and Scientists*. Boca Raton: Chapman & Hall/CRC Press.

Polyanin, A. D., Zaitsev, V. F. & Moussiaux, A. (2002). *Handbook of First Order Partial Differential Equations*. London: Taylor & Francis.

Wazwaz, Abdul-Majid (2009). *Partial Differential Equations and Solitary Waves Theory*, Higher Education Press.